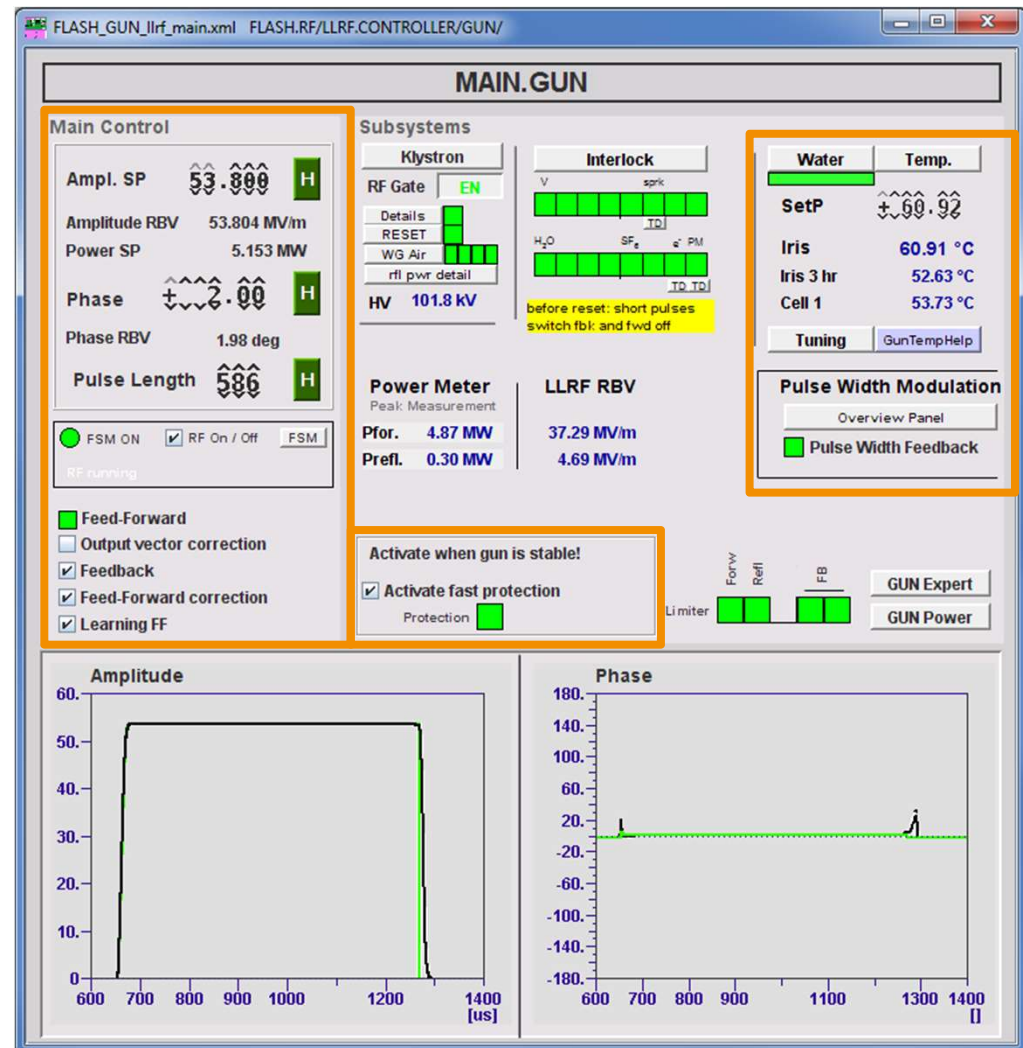


FLASH RF gun developments.

Sven Pfeiffer for the LLRF team
FEL Seminar
Hamburg, 19.04.2016

Outline

- > Introduction
- > LLRF
 - Feedback & Limitations
 - Learning Feedforward
- > Pulse Width Modulation
 - RF gun cooling system
 - Temperature estimation
 - Precision temperature control
- > Fast Protection
 - The why and wherefore
- > Current problems
 - After start-up



Outline

> Introduction

> LLRF

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- Learning Feedforward

> Pulse Width Modulation

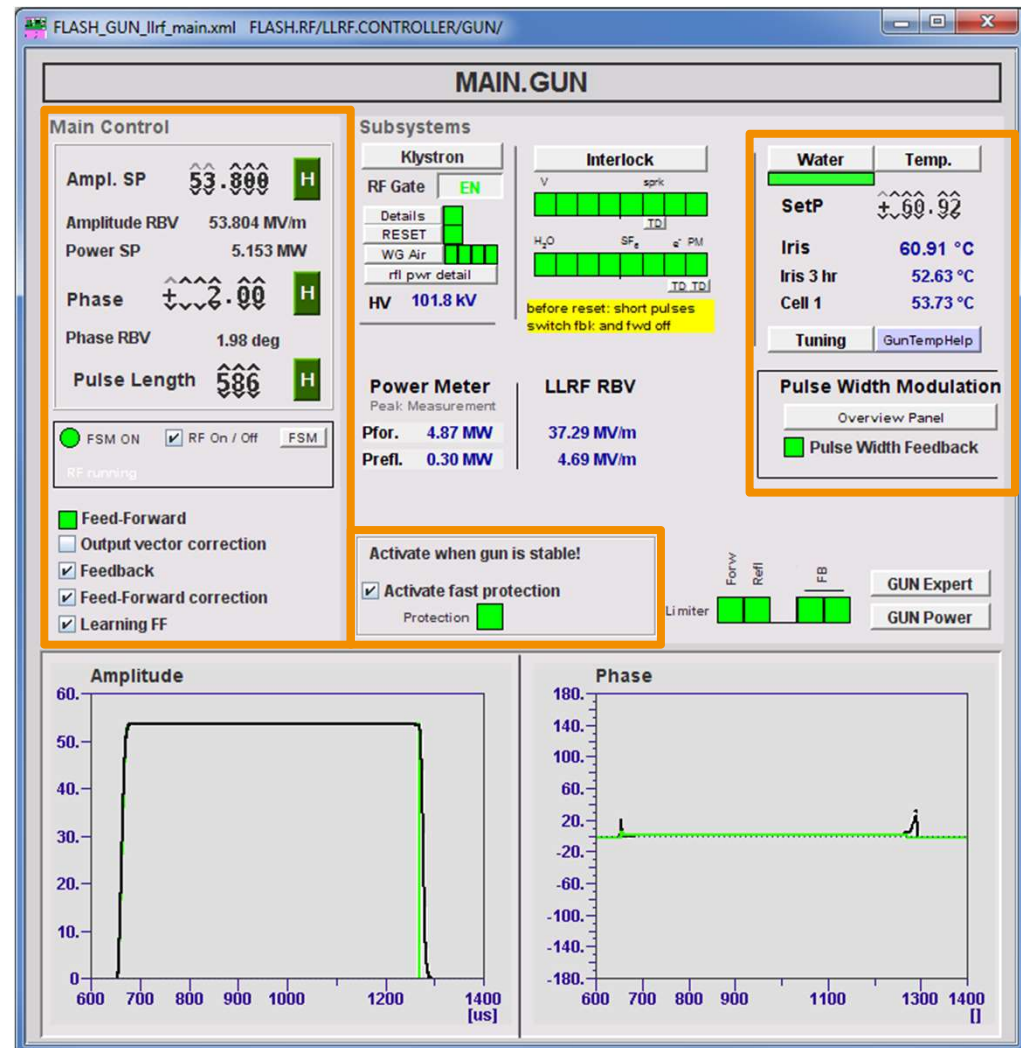
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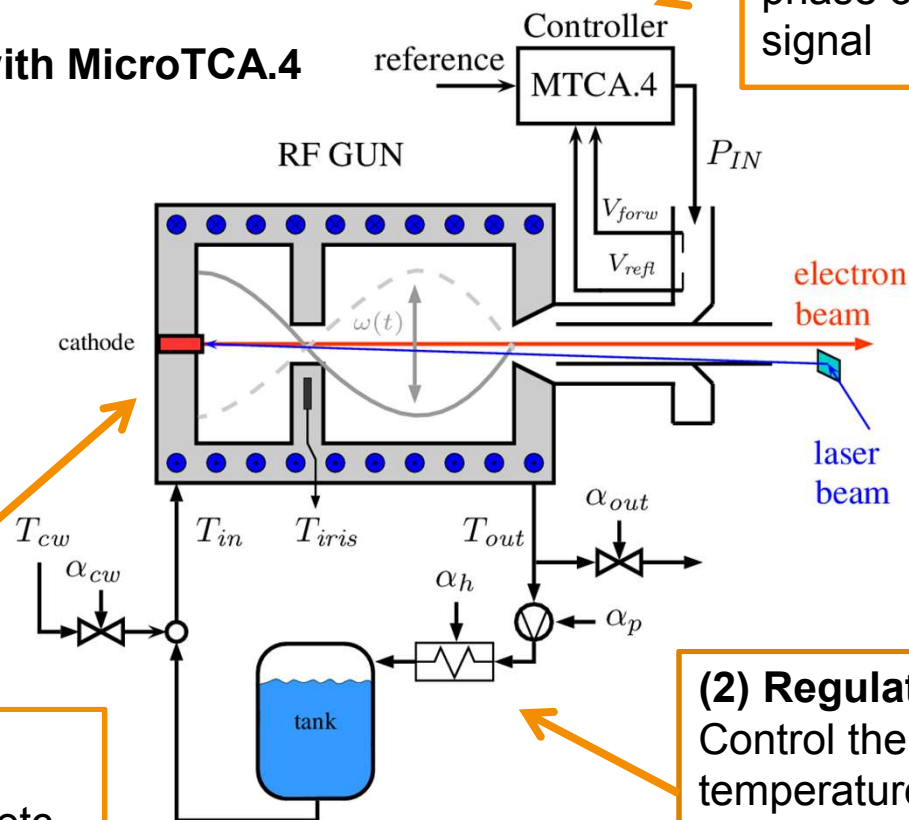
- After start-up



Introduction

1.3 GHz SWS, Pulsed mode @ 10 Hz,
Forward power ≈ 5 MW (average power ≈ 50 kW)
Pulse length up to 800 μ s \rightarrow 1% duty cycle

Since 01/2015 operated with MicroTCA.4



(1) Regulation - LLRF:
Control the amplitude and phase of virtual probe signal

(3) Protection:

Limiter for Output, FB, LFF etc.
Switch off the power to RF gun if necessary, e.g. spark

(2) Regulation - Water:
Control the RF gun temperature \rightarrow keep it on (slightly below) its resonance frequency

Outline

> Introduction

> LLRF

- Feedback Loop
- Concepts & Achievement

> Pulse Width Modulation

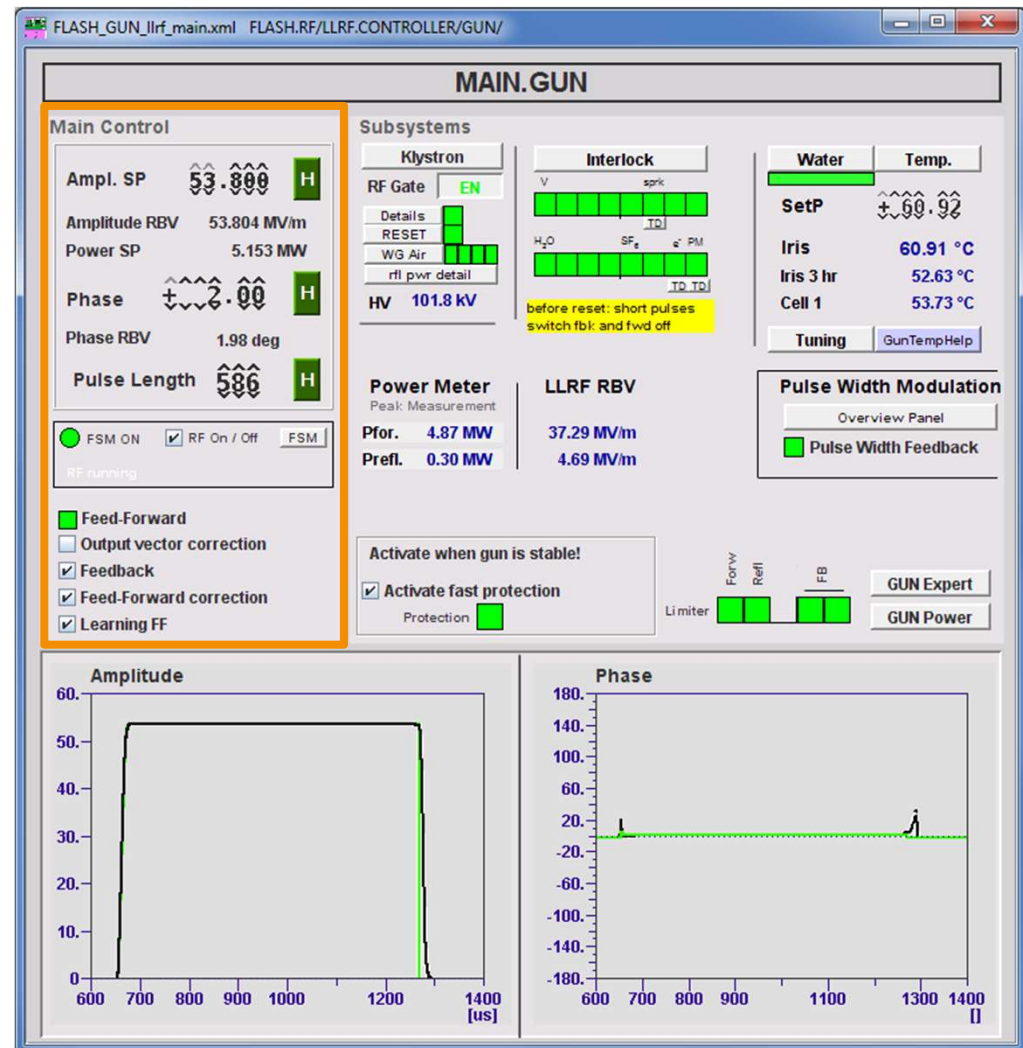
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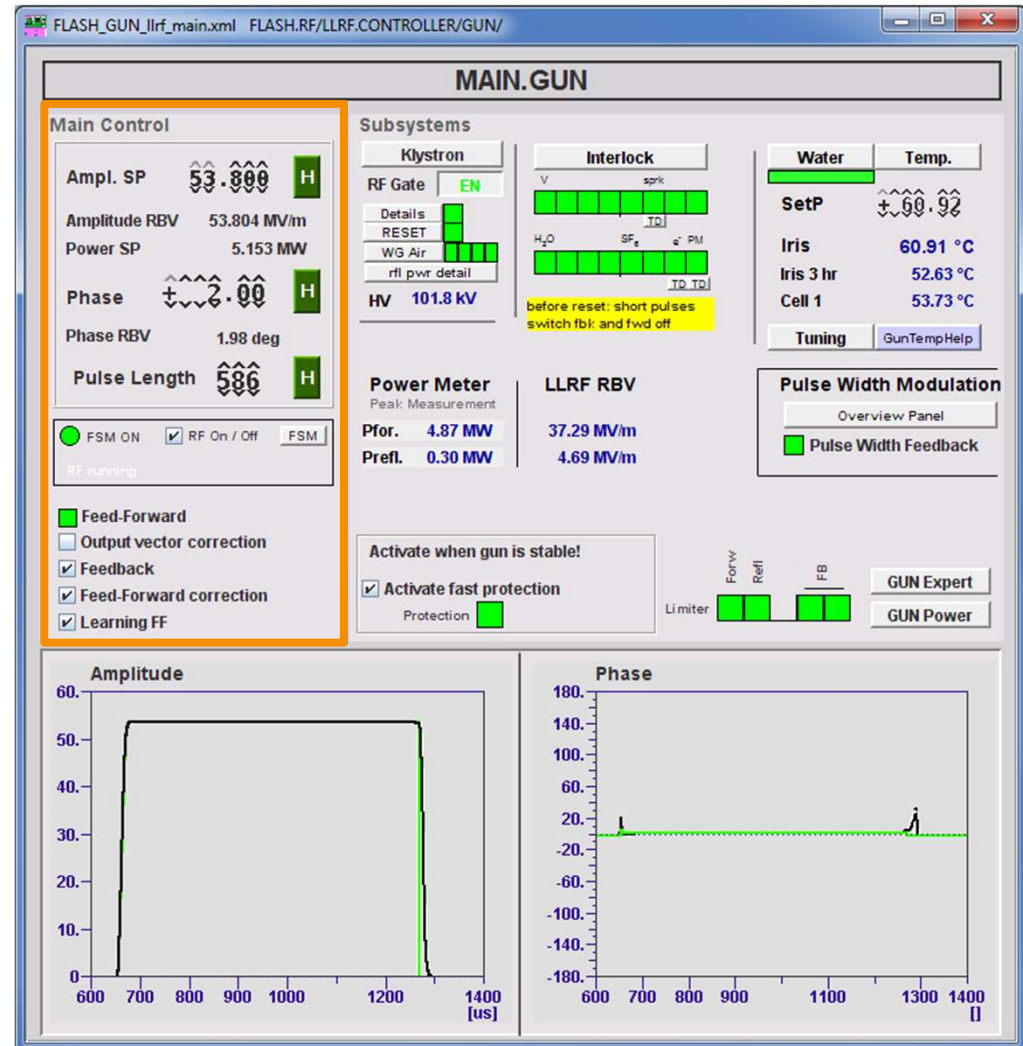


LLRF Regulation

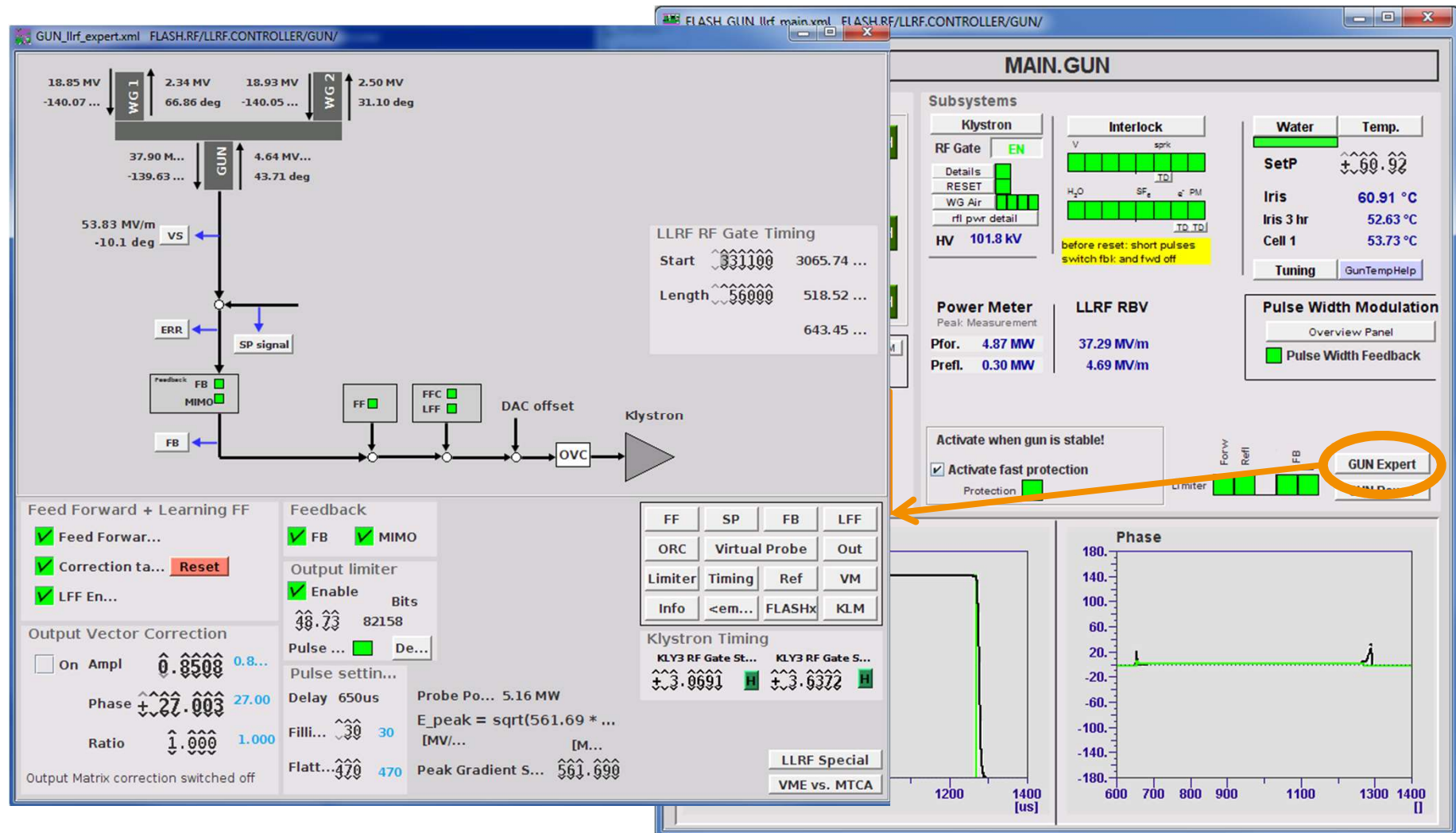
Main.GUN Panel

LLRF

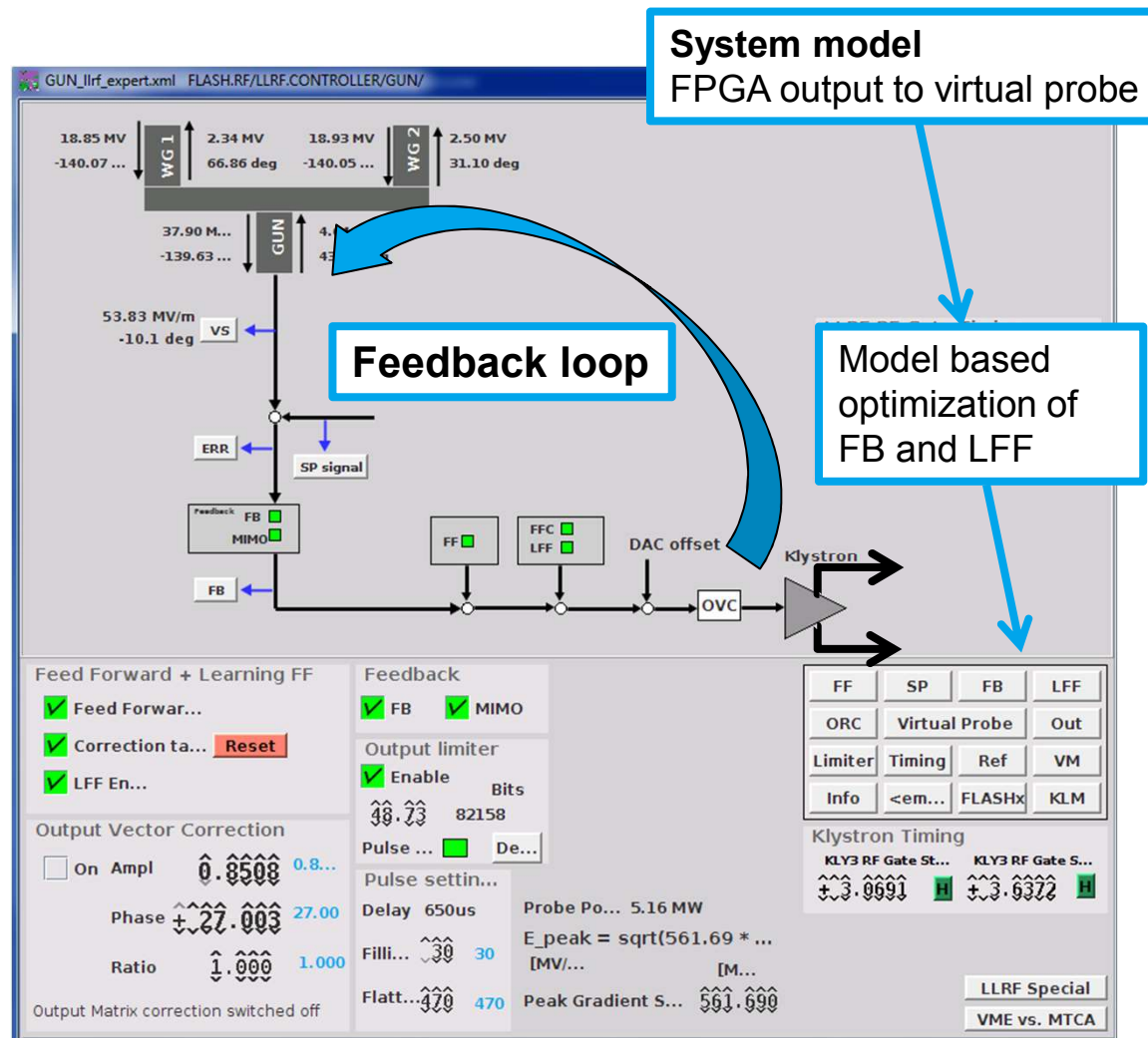
- > Ampl. SP [MV/m]
 - (new: before power SP [MW])
- > Phase SP [deg]
- > Pulse length [μ s]
- > Feedforward
- > Feedback
- > OVC, LFF etc.



LLRF Regulation



LLRF Regulation

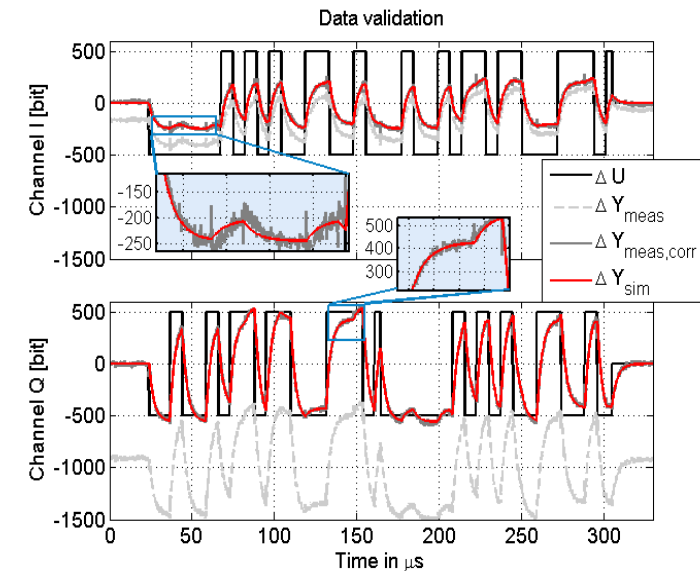


Small signal system model

$$\begin{pmatrix} \Delta Y_I(z) \\ \Delta Y_Q(z) \end{pmatrix} = \begin{bmatrix} G_1(z) & -G_2(z) \\ G_2(z) & G_1(z) \end{bmatrix} \begin{pmatrix} \Delta U_I(z) \\ \Delta U_Q(z) \end{pmatrix}$$

Identified parameters:

- I/Q gains as function of frequency
- Cross-couplings
- Bandwidth ~ 52 kHz
- Loop delay ~ 1.4 μ s



LLRF Regulation

Feedback concepts

Goal: $dA/A < 0.01\%$
 $d\phi < 0.01 \text{ deg (rms)}$

1) Output-Vector Correction (OVC - Server)

→ Drift compensation

2) Learning Feedforward (LFF - Server)

→ Minimize repetitive errors from pulse to pulse

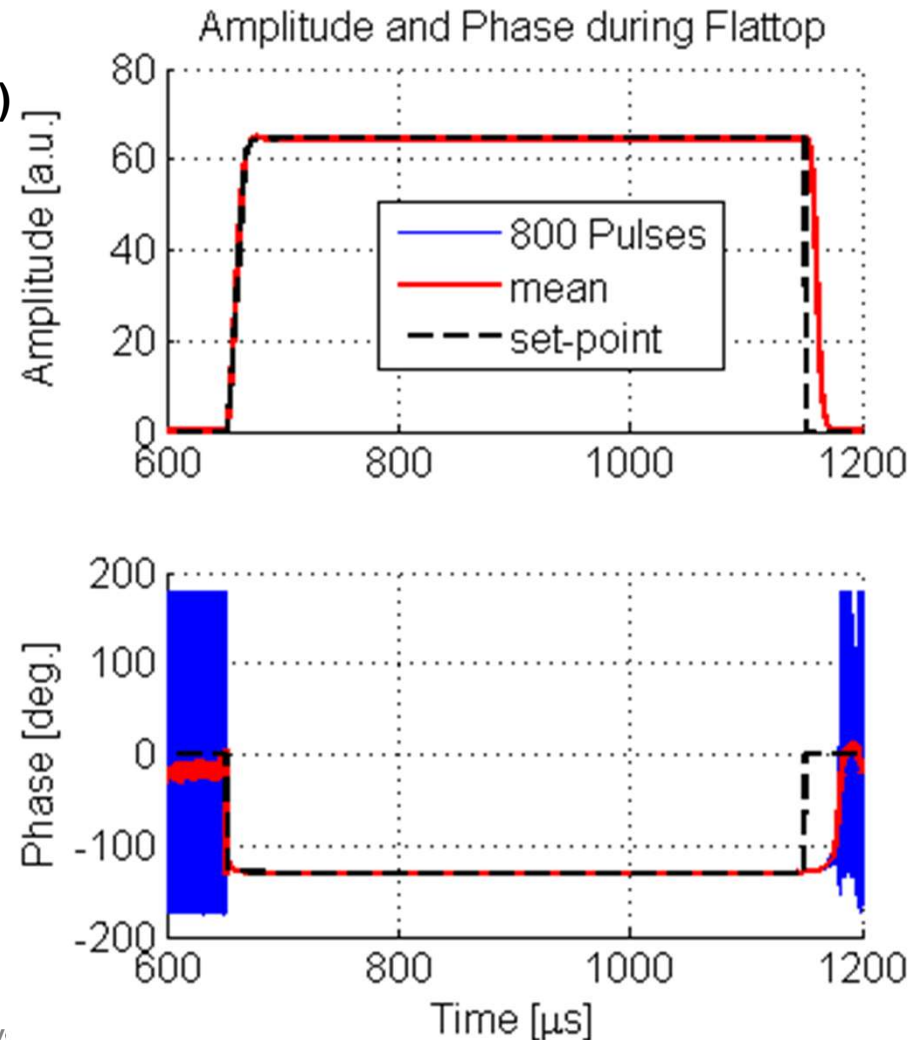
3) MIMO feedback (FB - FPGA)

→ Intra-pulse feedback

- **Main limitation:** Loop delay $\approx 1.4 \mu\text{s}$

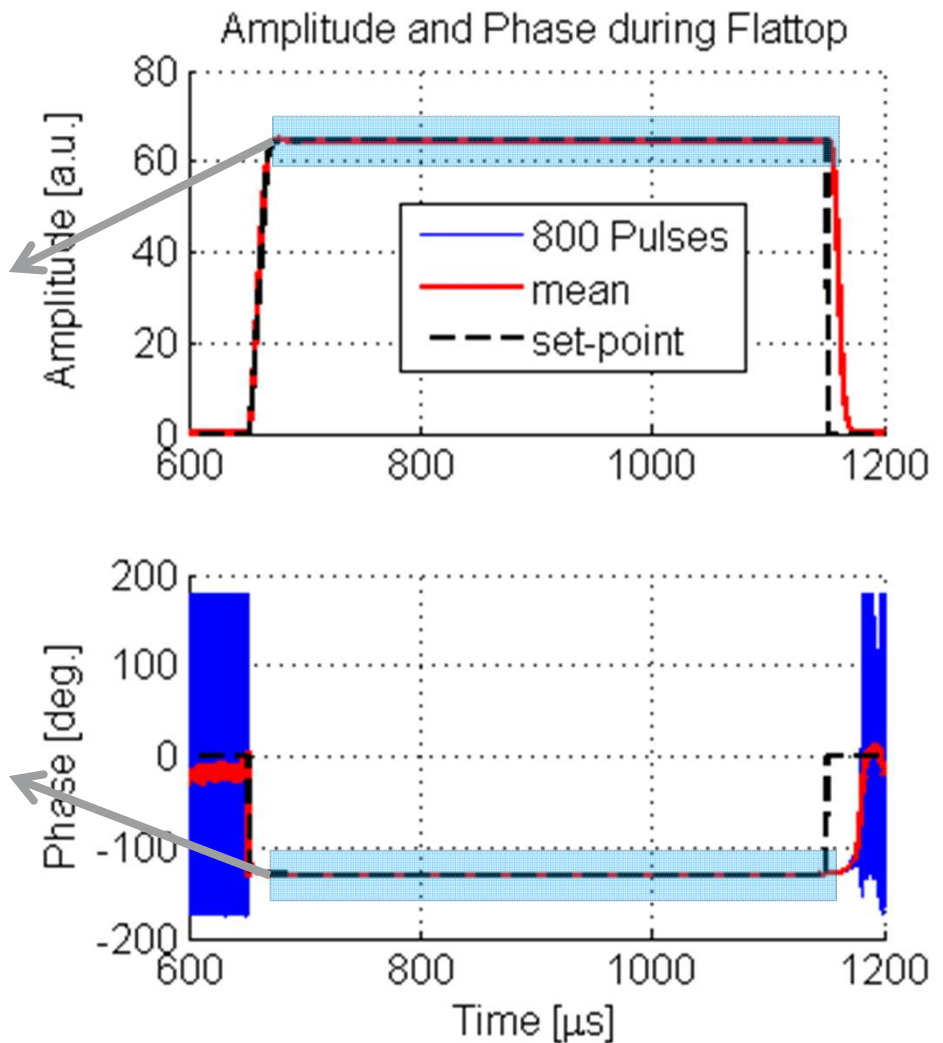
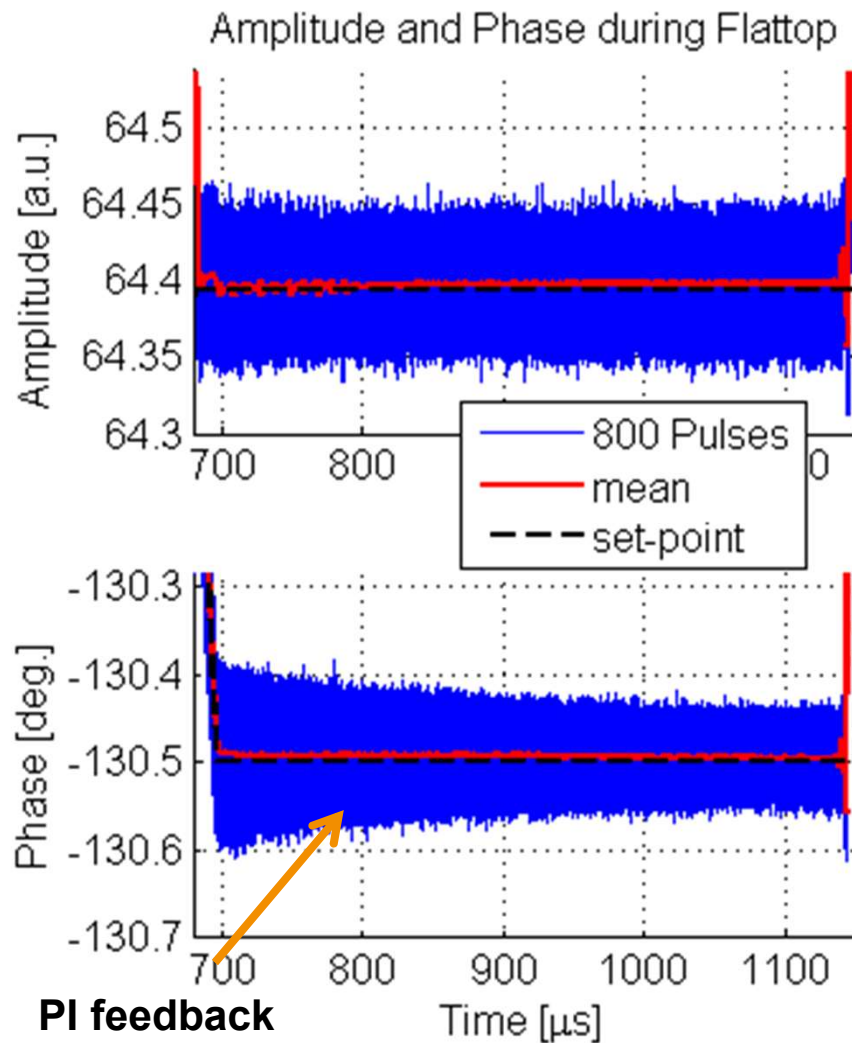
→ limits control gain

→ max. FB gain 2-3; SRF $\approx 20\text{-}40$ (!)



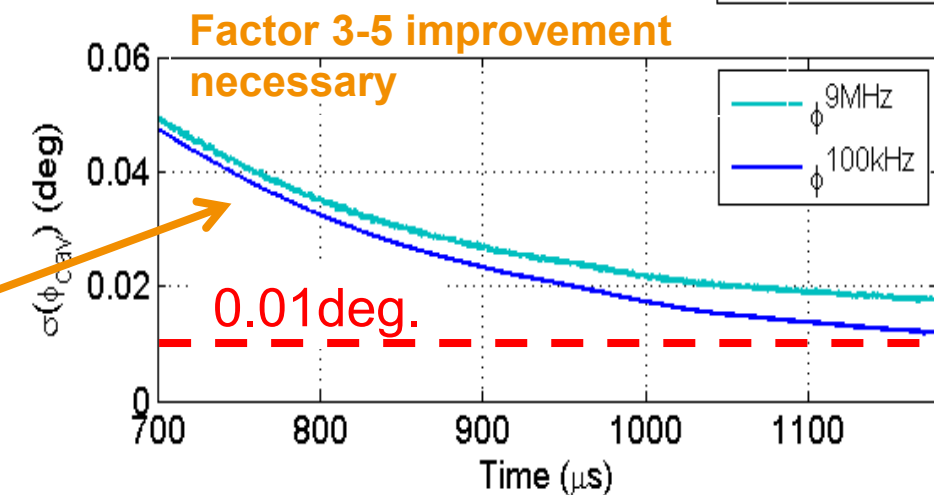
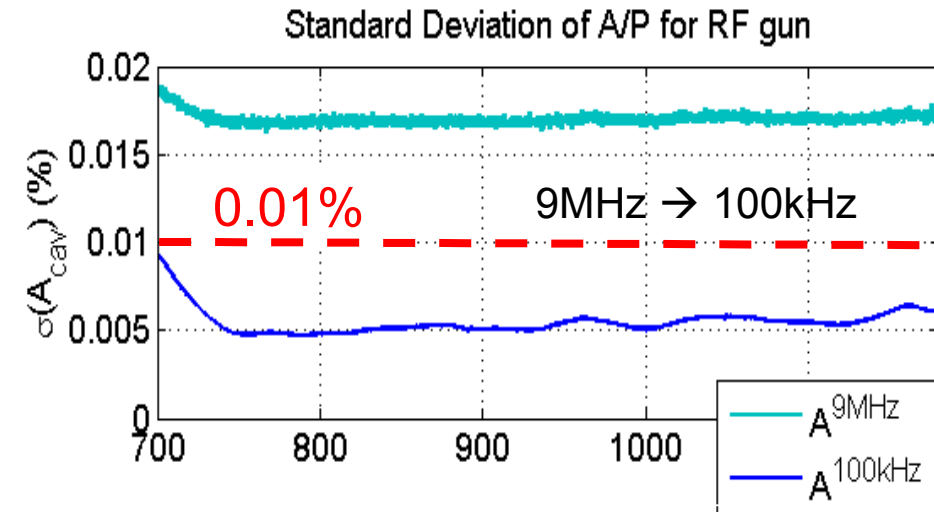
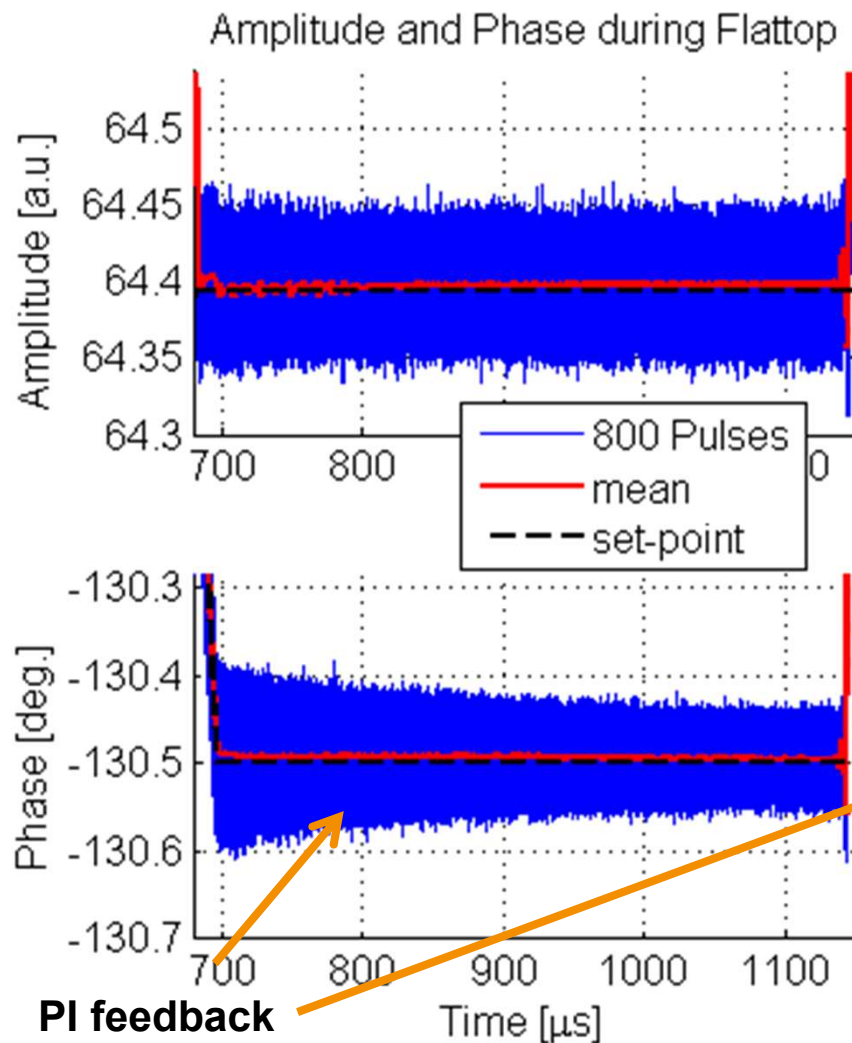
LLRF Regulation

Goal: $dA/A < 0.01\%$
 $d\phi < 0.01 \text{ deg (rms)}$



LLRF Regulation

Goal: $dA/A < 0.01\%$
 $d\phi < 0.01 \text{ deg (rms)}$



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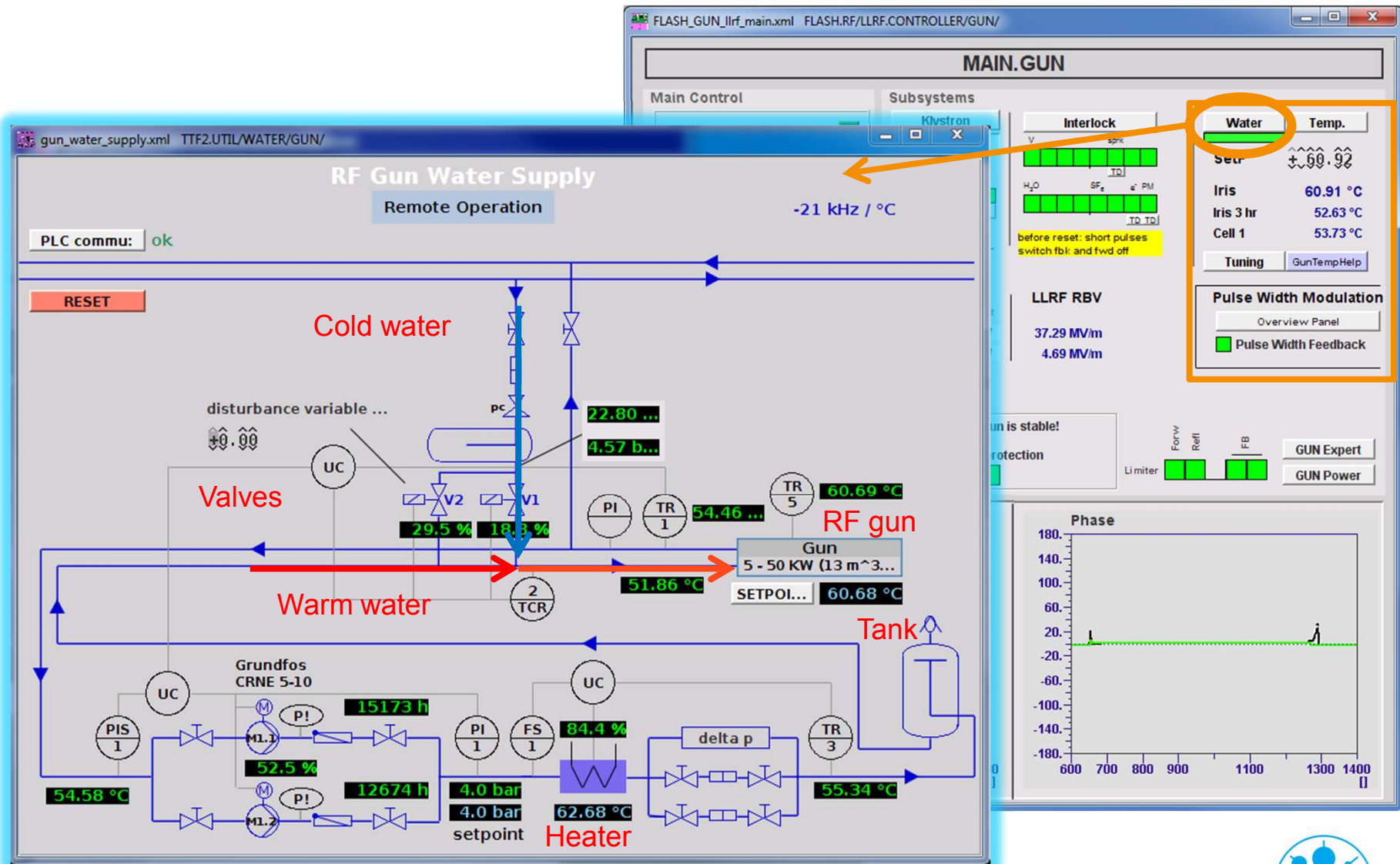
> Current problems

- After start-up

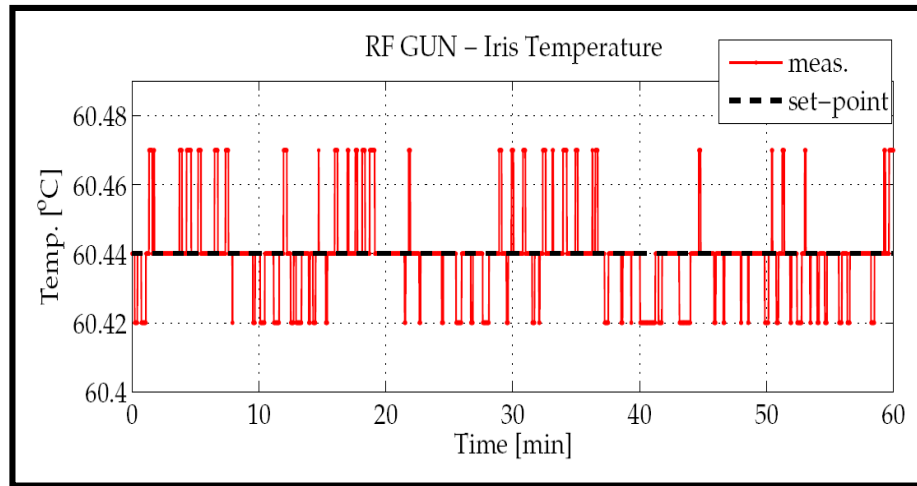
> Outlook



RF gun cooling system



RF gun cooling system



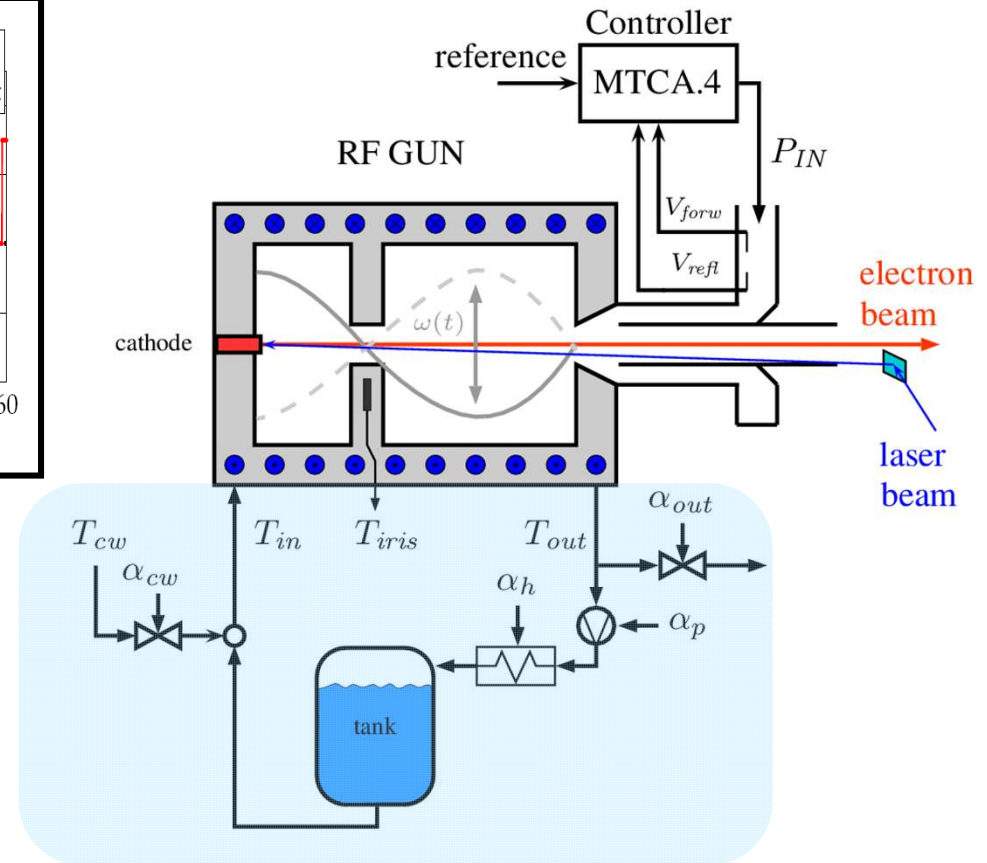
Long term error ± 1 bit (**about 14mK rms**)

@Resolution (12 bit ADC)
of 0.02 K – 0.03 K

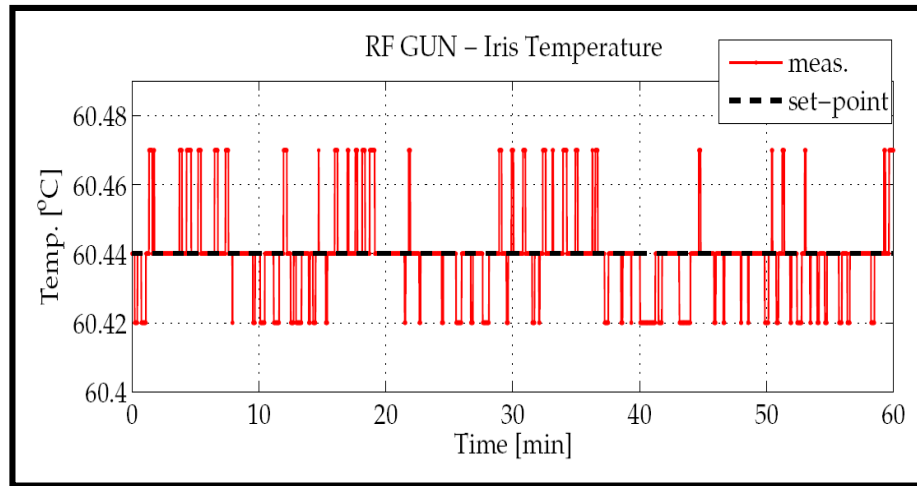
**Required stability for $d\phi < 0.01$ deg
without LLRF control:**

$$\Delta T = \frac{\tan \psi \cdot f}{2 Q_L K_{fT}} \approx \frac{d\phi \cdot f}{2 Q_L K_{fT}} < 0.45 \text{mK},$$

$$(f = 1.3 \text{GHz}, Q_L = 12000, K_{fT} = -21 \text{kHz/K})$$



RF gun cooling system



Long term error ± 1 bit (**about 14mK rms**)

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**Required stability for $d\phi < 0.01$ deg
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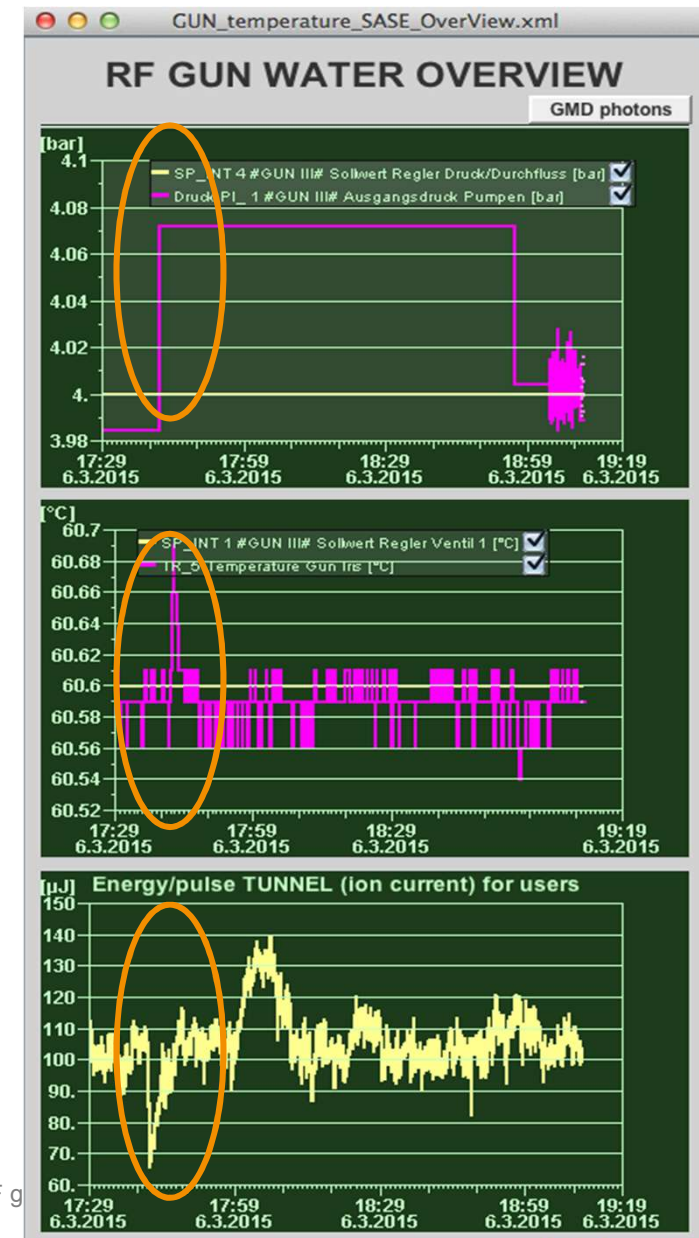
$$\Delta T = \frac{\tan \psi \cdot f}{2 Q_L K_{fT}} \approx \frac{d\phi \cdot f}{2 Q_L K_{fT}} < 0.45 \text{ mK},$$

$$(f = 1.3 \text{ GHz}, Q_L = 12000, K_{fT} = -21 \text{ kHz/K})$$

Pressure
+0.09bar

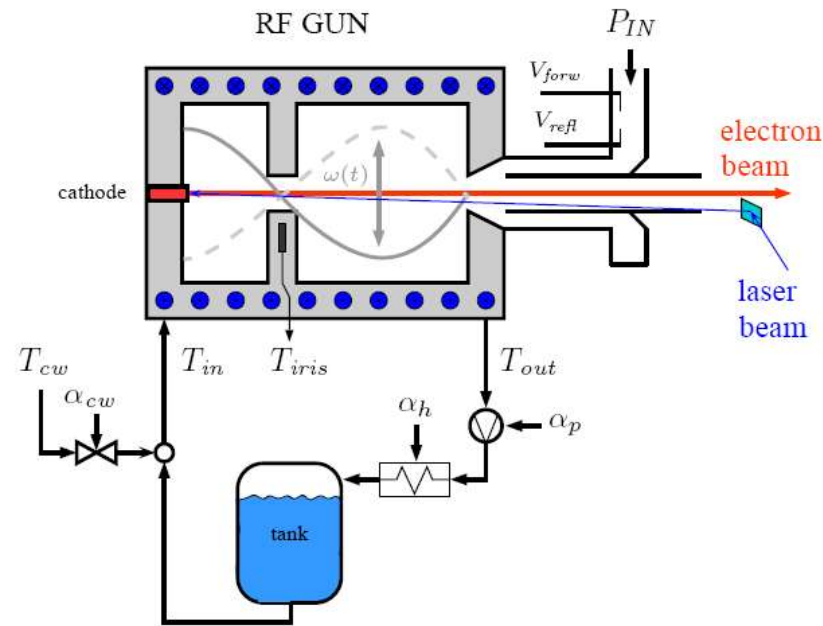
T_{IRIS}
+100mK

SASE
-35uJ

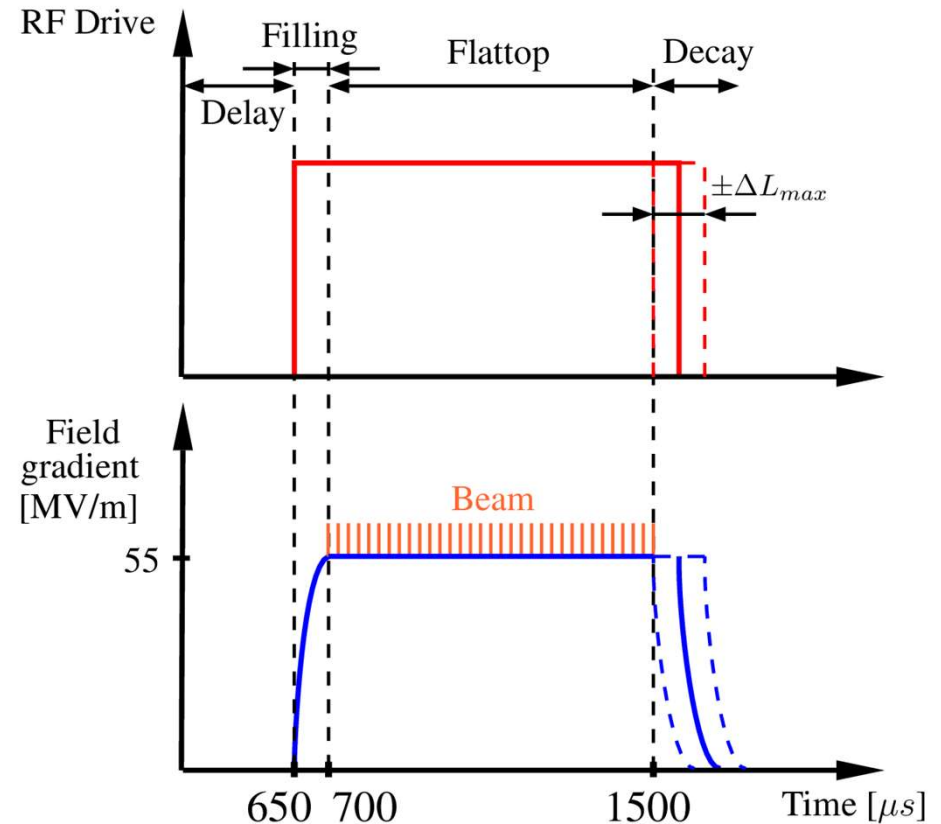


Pulse Width Modulation

Idea: Usage of LLRF Signals



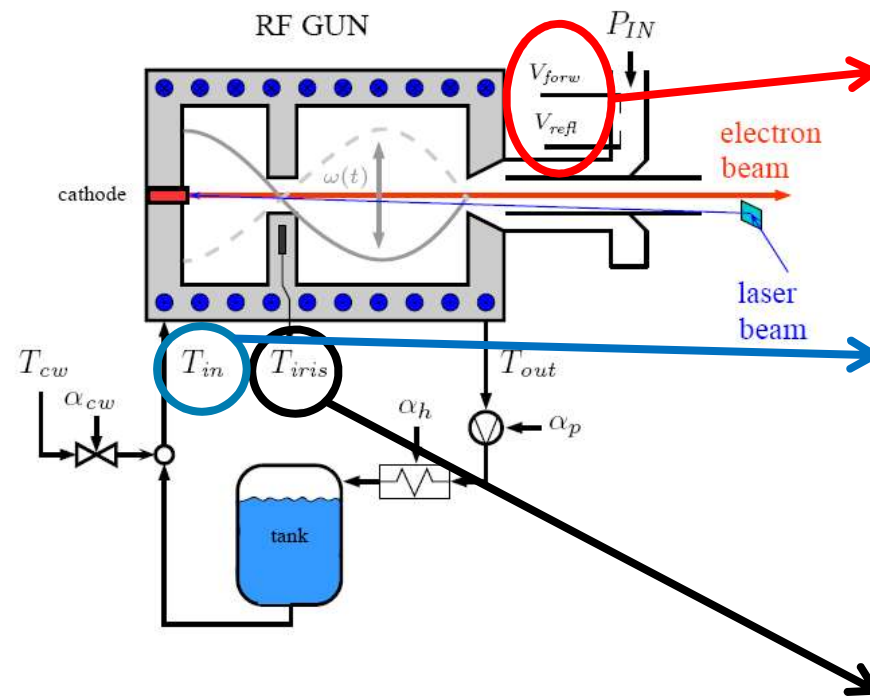
Use pulse width modulation to control the dissipated power (heat balance) to the RF gun body within pre-defined limits



Needed is a high precision temperature estimation with no time delay for pulse to pulse feedback

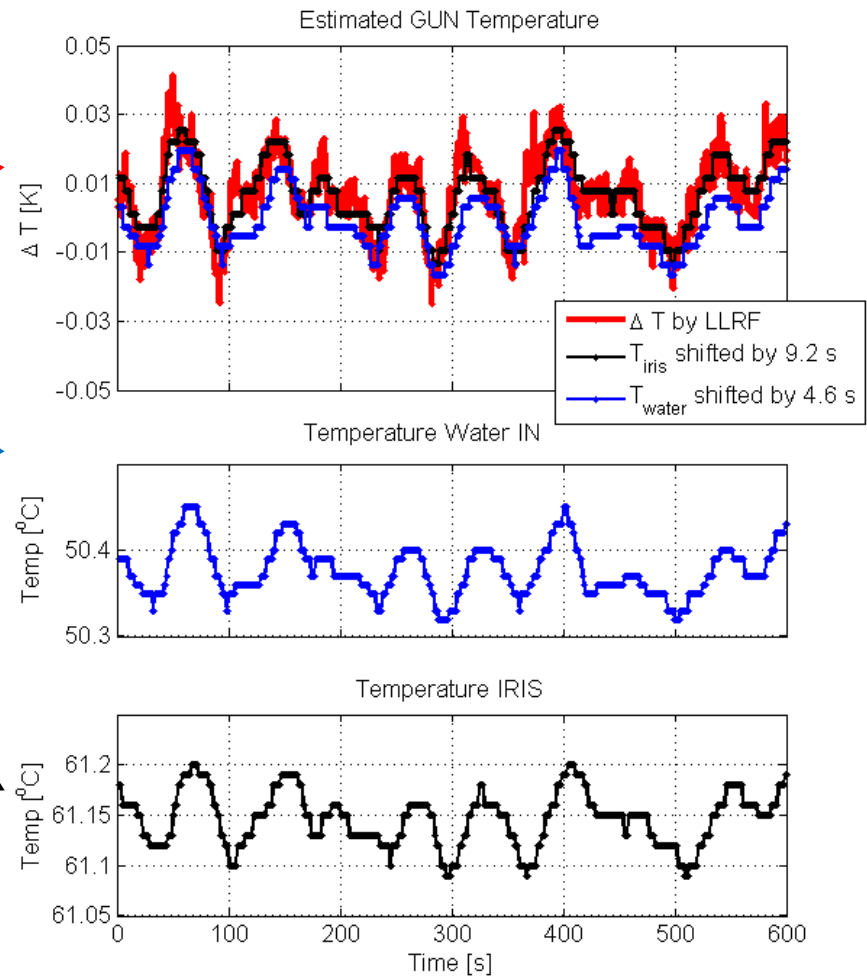
Pulse Width Modulation

Idea: Usage of LLRF Signals



Delayed T_{IRIS} (9s) and T_{IN} (5s) information

- Transition from cavity body to sensor
- Low pass behavior of temp. sensor

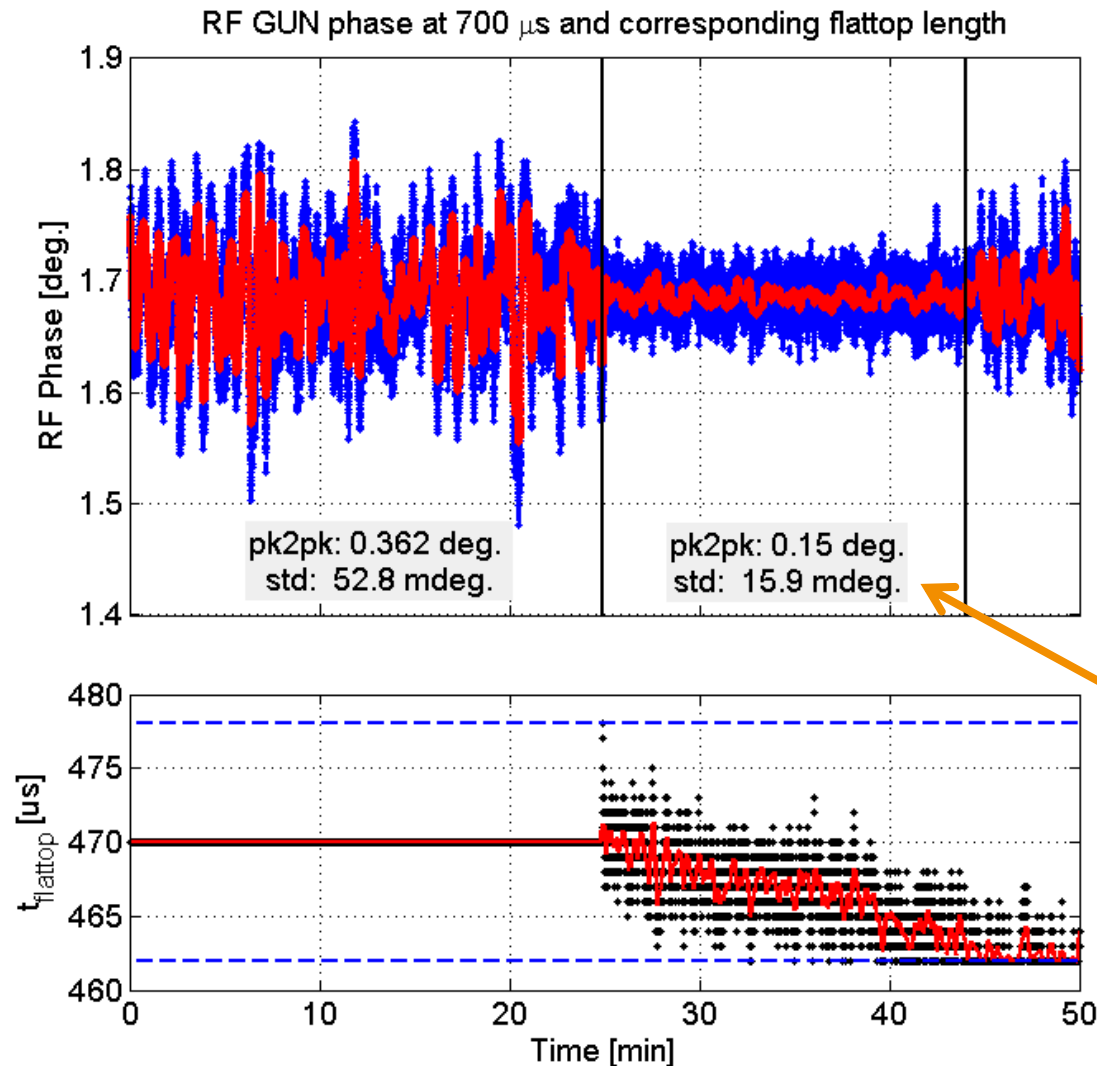


FLASH RF GUN data
Temp. sensor (12 bit ADC)



Pulse Width Modulation

Blue: single pulse, Red: mean 100 pulses (10s@10Hz)



- > RF GUN phase at 1st beam position (700 μs) for 50 minutes
- > Without and with modulation to minimize disturbances from cooling water circuit
Pulse to pulse compensation (10 Hz)
- > **Improvement for phase x3**
($d\phi = 53 \text{ mdeg.} \rightarrow 16 \text{ mdeg.}$)
- > **RF GUN temperature stabilized by x5** (from 14 mK \rightarrow 3 mK)
- > **Running @ FLASH, PITZ, (XFEL)**



Pulse Width Modulation

Goal: $dA/A < 0.01\%$
 $d\phi < 0.01 \text{ deg (rms)}$

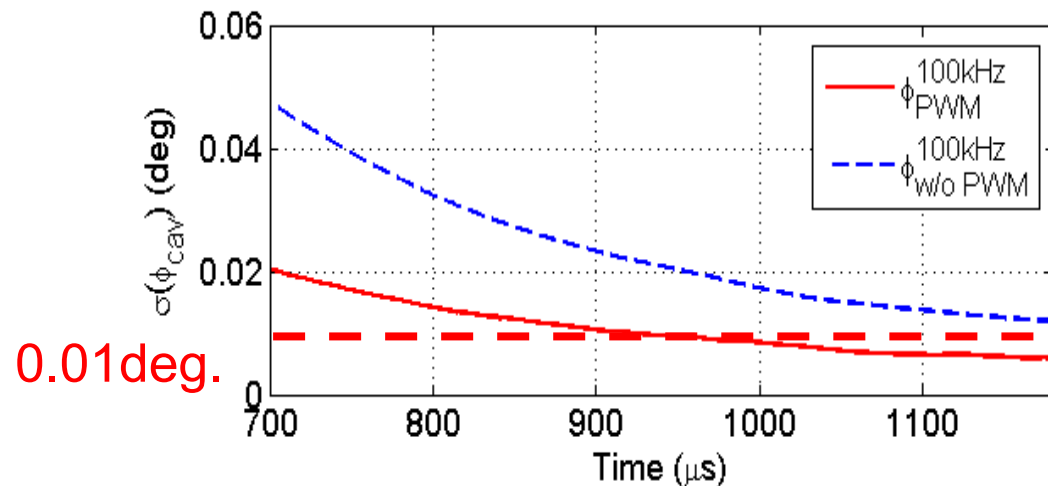
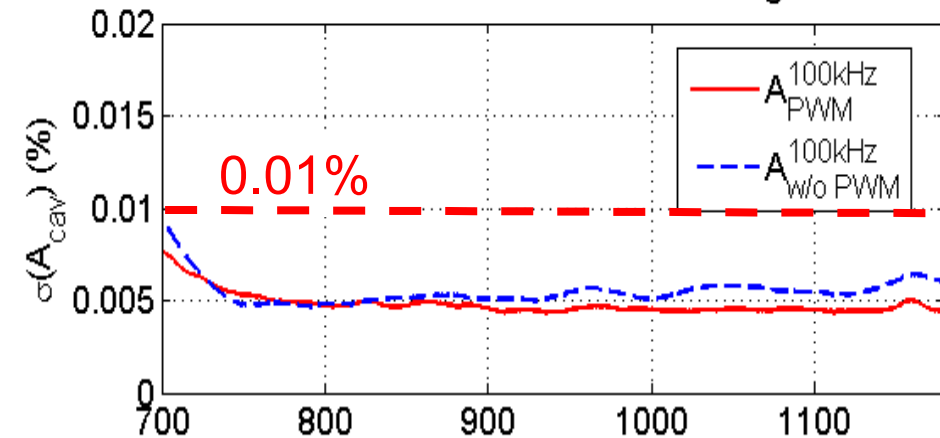
Remember:

- > Factor 3-5 improvement in phase is necessary using only LLRF control

Applying PWM:


- > No improvement of RF amplitude
 - Detuning affects mainly the RF phase
- > Great improvement in standard deviation of RF phase
- > Achieved by using disturbance minimization of detuning with precision temperature control

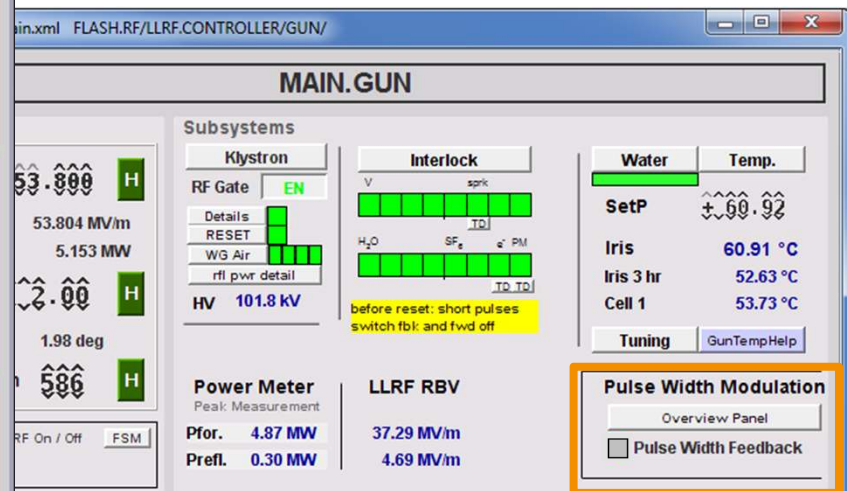
Standard Deviation of A/P for RF gun



Pulse Width Modulation – Panel



- PWM Feedback check box
- Set-point (automatically computed)
- Status indicator 
- Initialization (settings before PWM)
- Manual (set-up, problem handling)



- With Pulse Width Modulation
- Start-up of RF gun → next slide
- Without Pulse Width Modulation



Additional Info

> Using pulse width modulation – panel for start-up of RF gun



Direct response

RF gun is in resonance, to cold or to warm

→ Relative detuning / temperature information

→ What is the current optimal Iris set-point etc.



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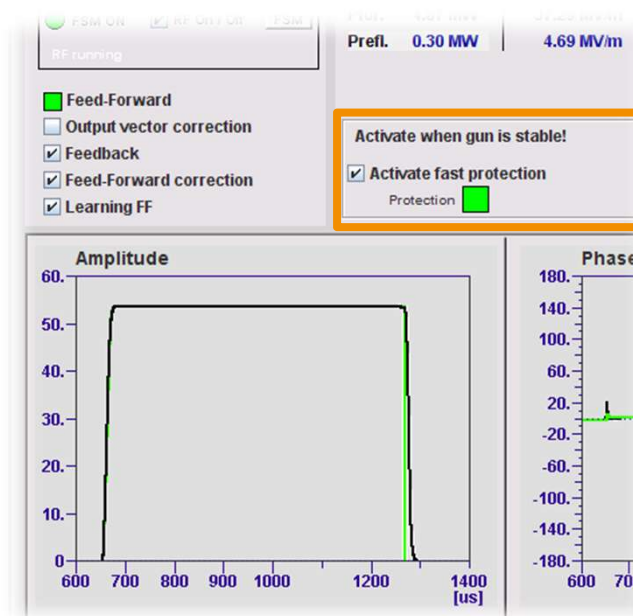
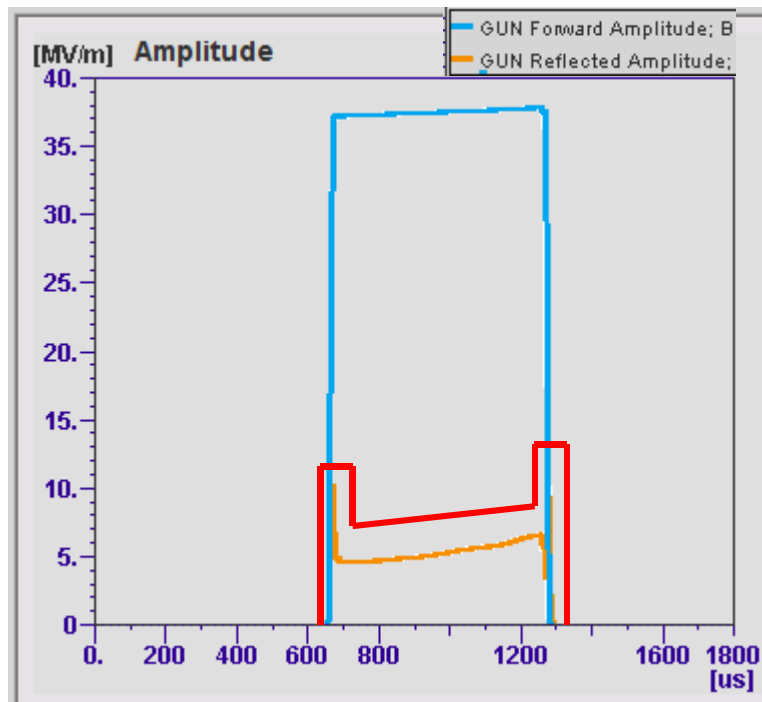
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Fast Protection

- Implementation in FPGA (L. Butkowski, C. Schmidt et al.)
- Threshold for reflected signal is defined (scaled by forward signal)
- Cut RF pulse if reflected signal is too high (sparks, detuning, etc.)



Fast Protection

➤ 6 Events since 01/2016 → no known false alarms

12.04.2016 12:05 S. Schreiber Hist: FLASH.RF/LLRF.CONTROLL

rf gun fast protection: events where the fast protection triggered

event 1: 12-Jan-2016 16:03 h tests, rf was off

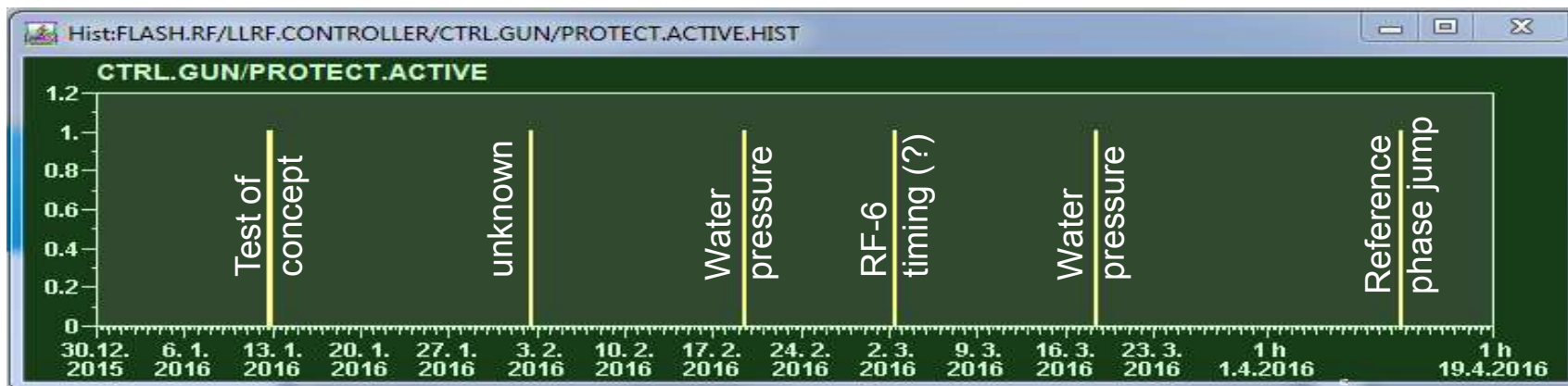
event 2: 2-Feb-2016 9:59 h unknown reason

event 3: 19-Feb-2016 10:52 h increase of cooling water pressure
http://ttfinfo.desy.de/elog/XMLlist?file=/TTFelog/data/2016/07/19.02_M/2016-02-19T10:53:12-03.x

event 4: 2-Mar-2016 11:50 h no DAQ data for this event, together with RF-6, could be timing issue
http://ttfinfo.desy.de/elog/XMLlist?file=/TTFelog/data/2016/09/02.03_a/2016-03-02T17:12:06-07.x

event 5: 18-Mar-2016 9:10 h cooling water pressure oscialltions
http://ttfinfo.desy.de/elog/XMLlist?file=/TTFelog/data/2016/11/18.03_a/2016-03-18T16:08:07-01.x

event 6: 11-Apr-2016 16:08 h sudden phase jump, also ACC1, llrf issue with reference RF
http://ttfinfo.desy.de/elog/XMLlist?file=/TTFelog/data/2016/15/11.04_a/2016-04-11T17:36:35-07.x



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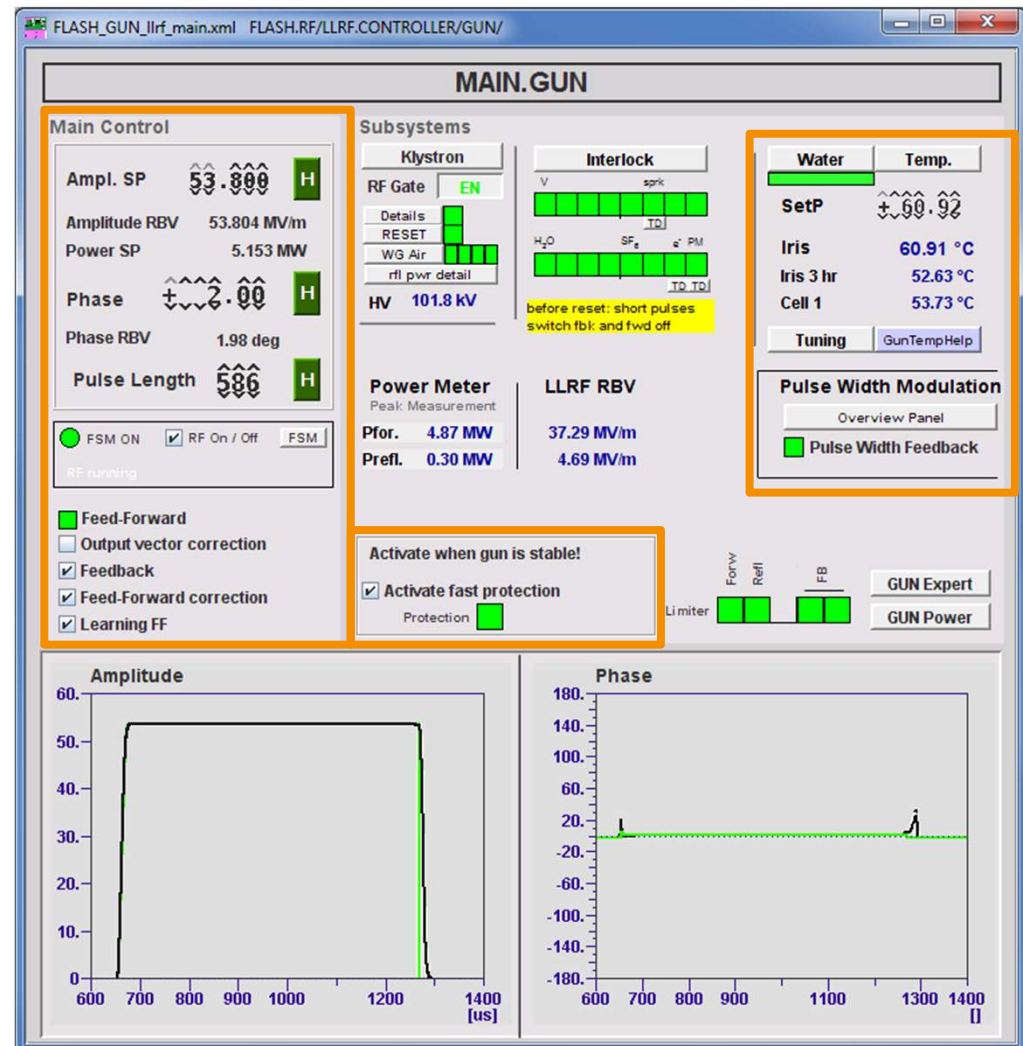
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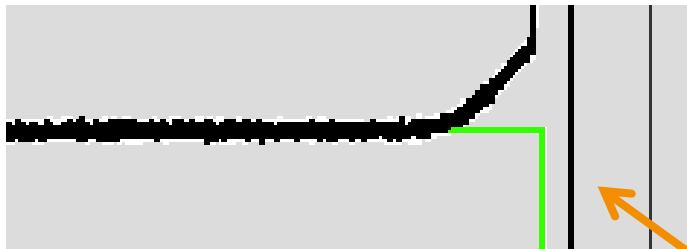
- After start-up



Current Problems

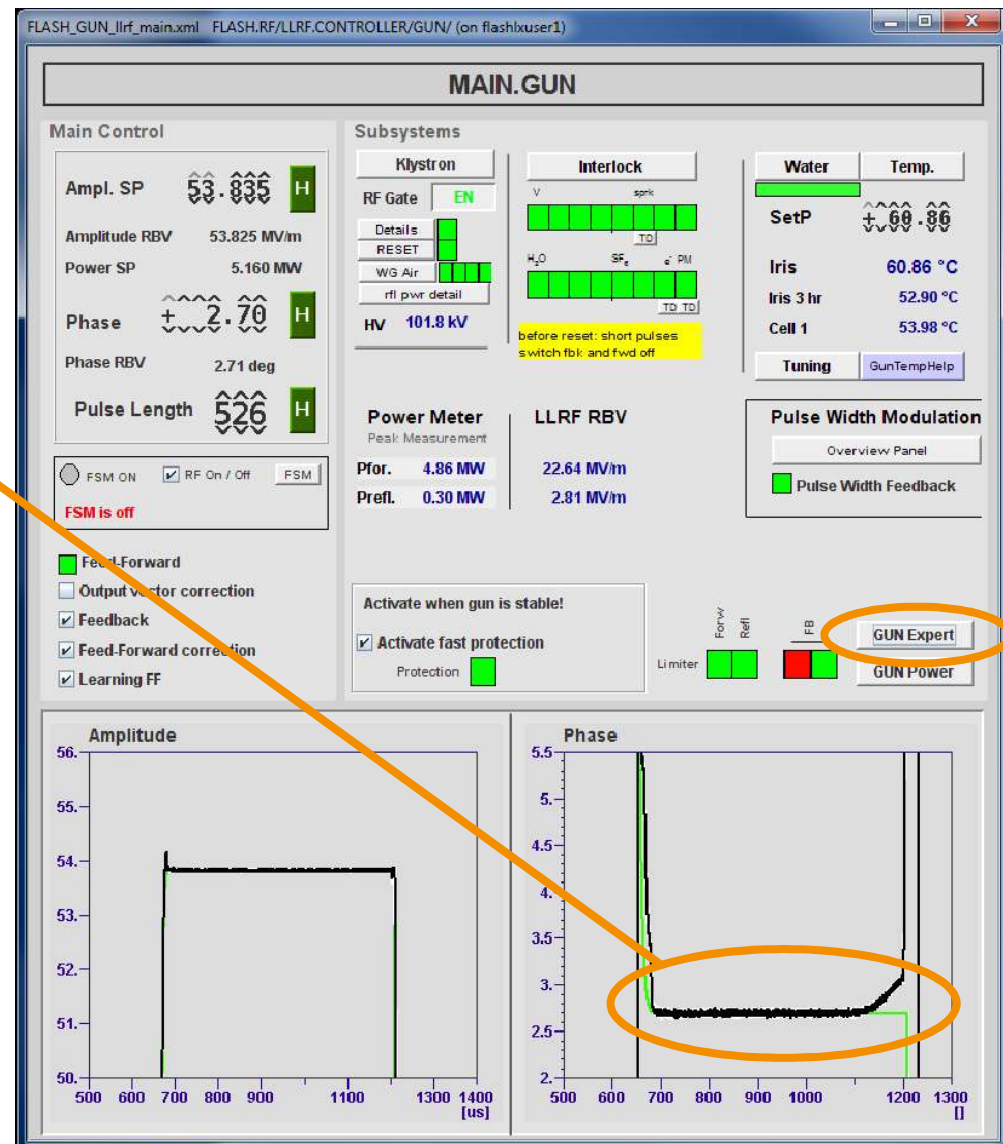
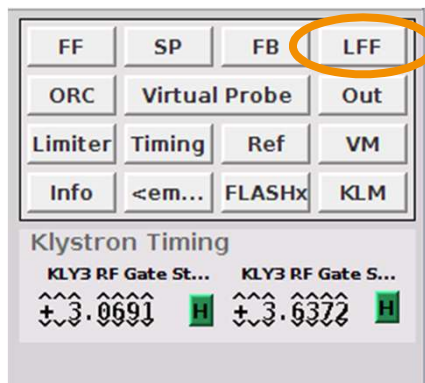
> After RF gun start-up

- Phase at end is not on set-point



> How to check?

- Look in LFF panel



Current Problems

> RF gun start-up without FB, LFF

(1) Adjust OVC before FB and LFF is enabled

(2) Enable FB, LFF

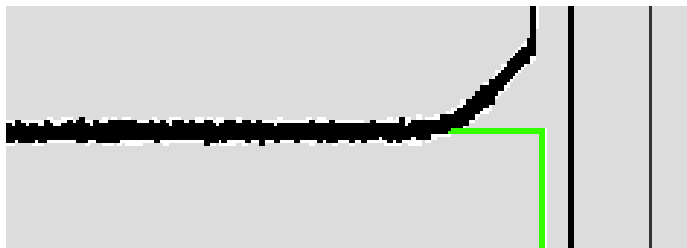
- FF correction are centered after a while
- FF correction limits: 7000 bits

→ $t = 0$

(3) FF correction tables 20 minutes later

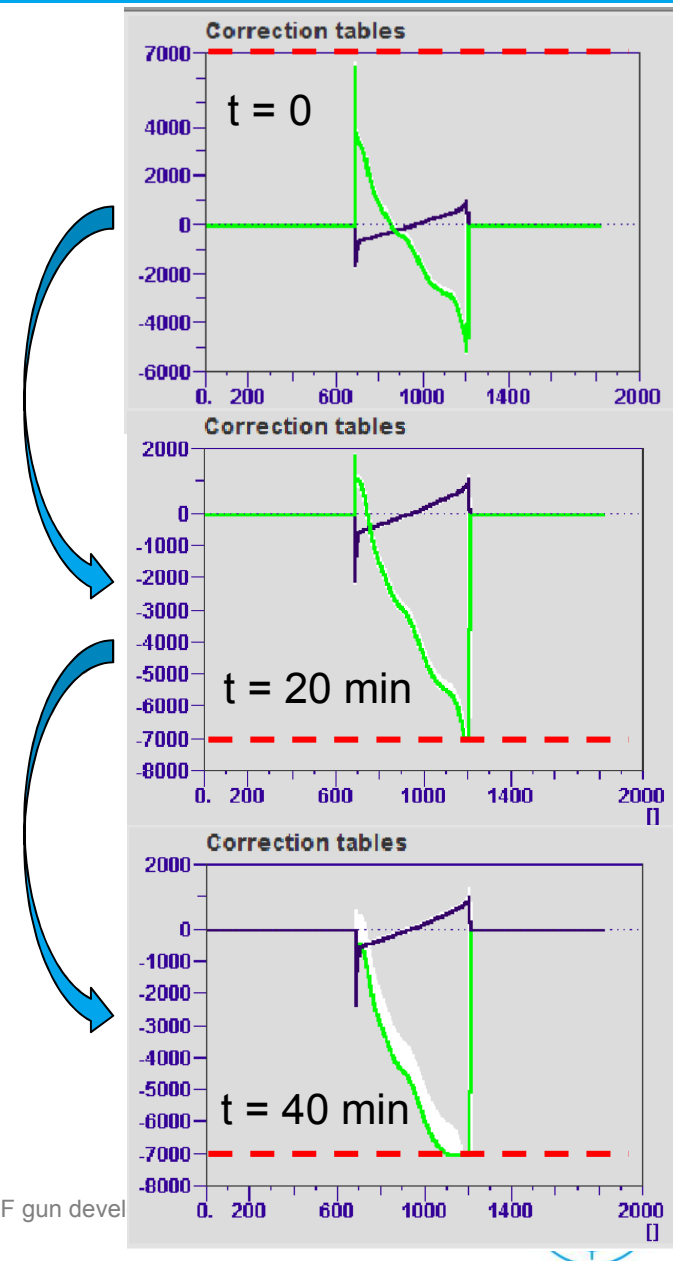
(4) After 40 minutes

- FF tables (Q channel) hits limit



Why?

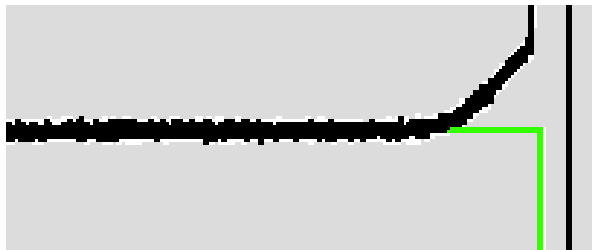
Slowly waveguide heating (guess)



Current Problems

> After RF gun start-up

- Phase at end is not on set-point



> Why?

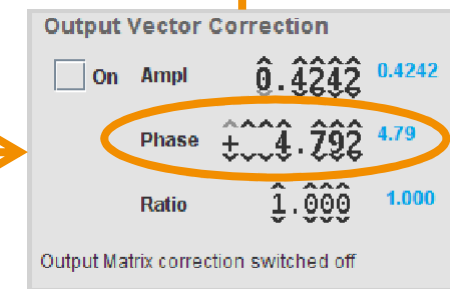
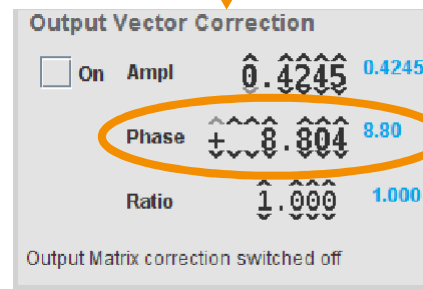
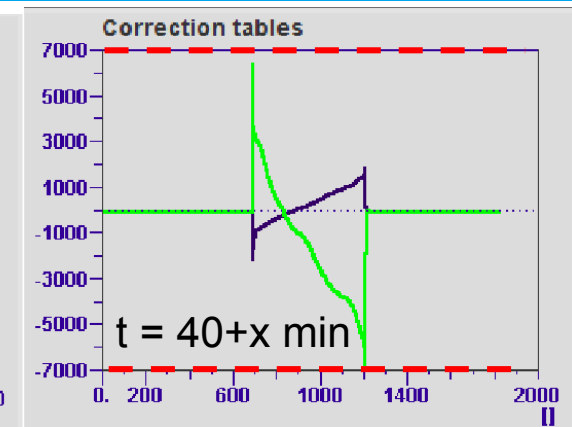
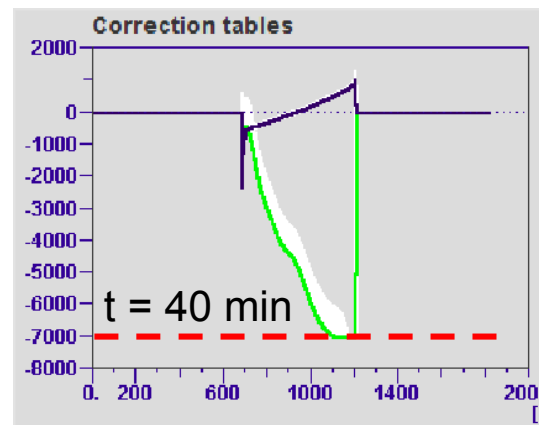
- Slowly waveguide heating (guess)

> How to check?

- Look in LFF panel

> What can I do?

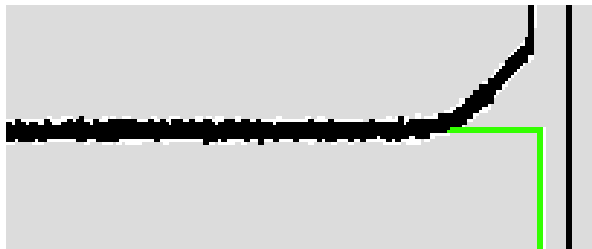
- Adjust OVC phase by ~ -4 deg



Current Problems

> After RF gun start-up

- Phase at end is not on set-point



> Why?

- Slowly waveguide heating (guess)

> How to check?

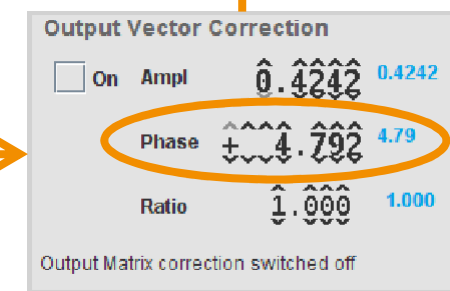
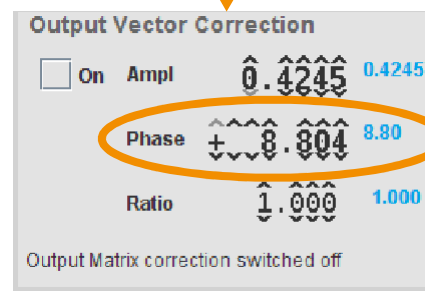
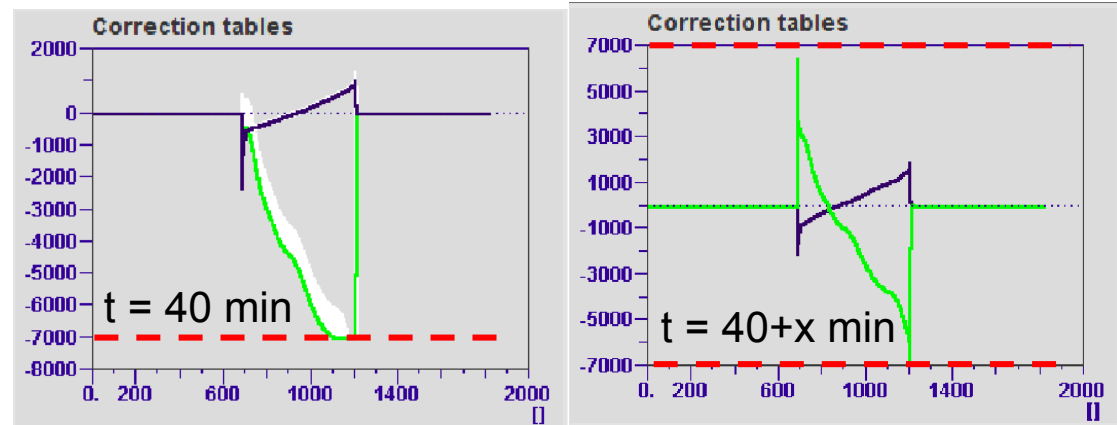
- Look in LFF panel

> What can I do?

- Adjust OVC phase by ~ -4 deg

> Why is it not done automatically?

- Most of the time OVC is OFF...
- OVC ON does not mean that its active...
- Active limiter deactivate OVC



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