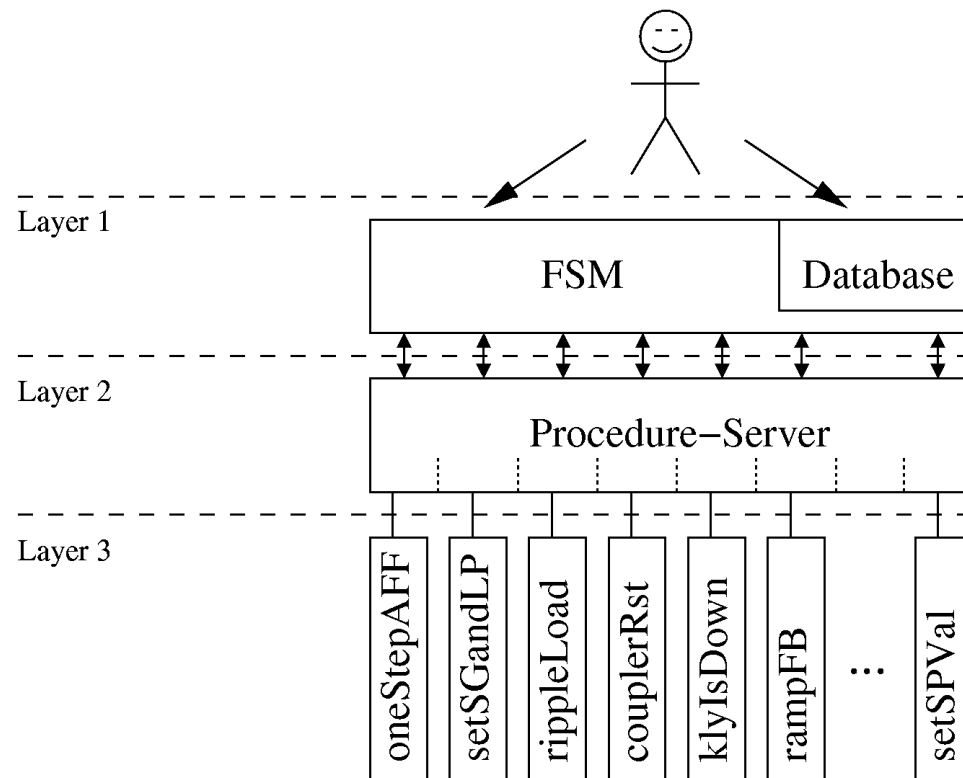

LLRF Automation and Adaptive Feedforward

`alexander.brandt@desy.de`



FSM-Architecture

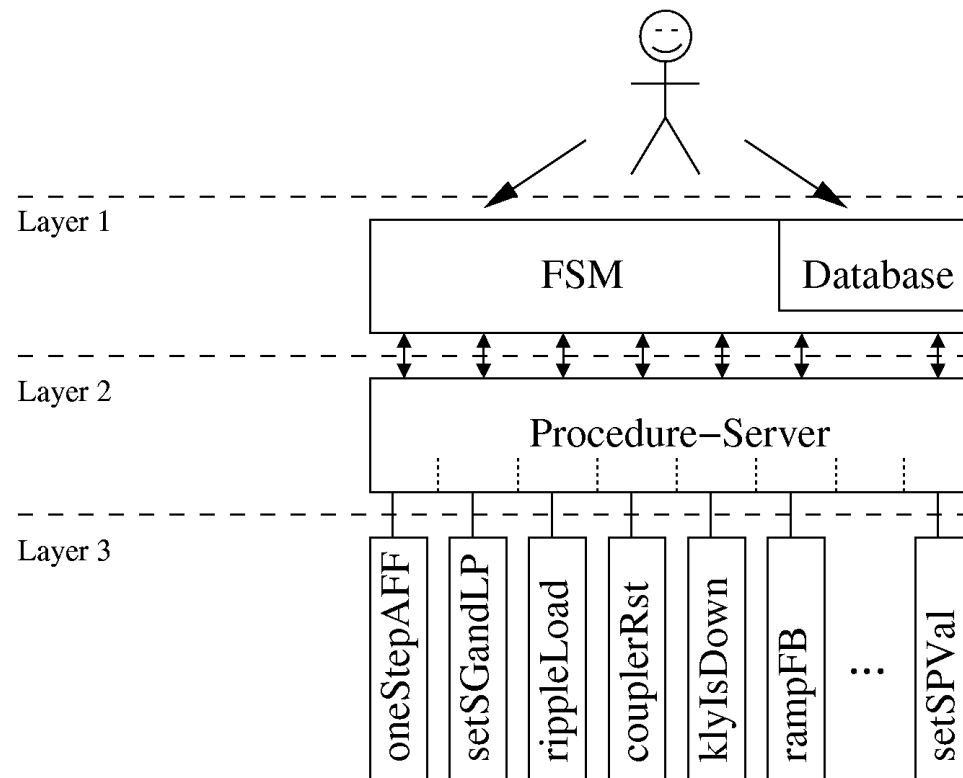


Procedures

- Compiled scripts of any programming language (and any Matlab-version)
- “Fire and forget”:
 - Invoke - Run - Return
 - “Stateless Procedures”
- E.g.:
 - Adaptive Feedforward**
 - Loop-Phase
- Web-Documentation
- Algorithms are identical for all RF-stations and read a config file



FSM-Architecture

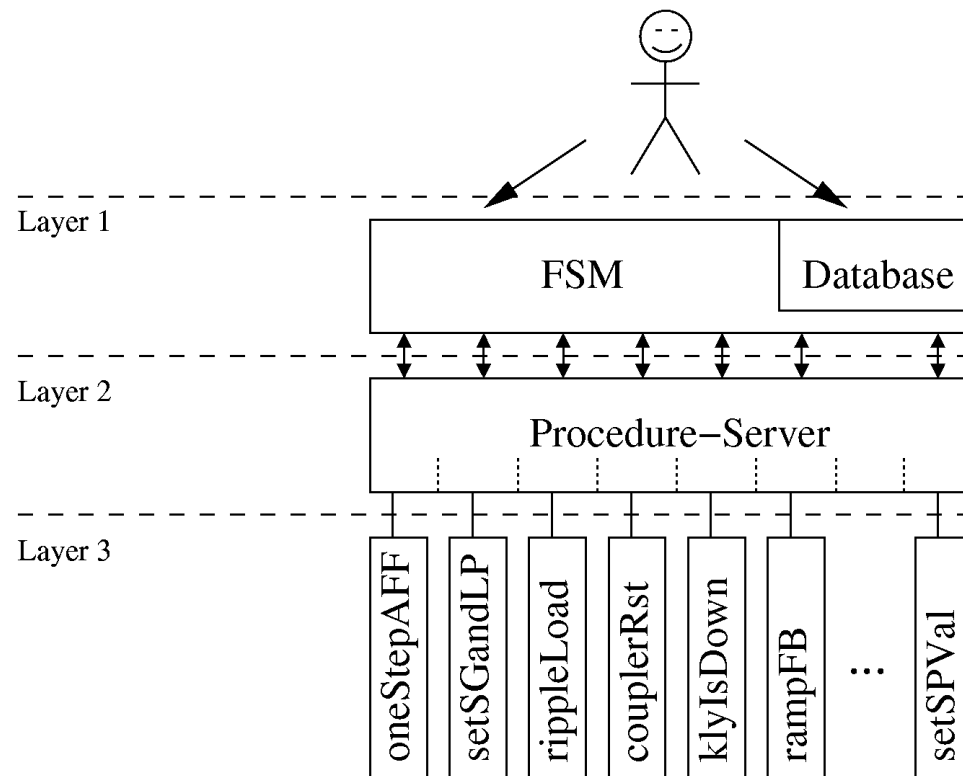


Procedure-Server

- Doocs-interface for configuration and access
- History-Display
- Email-Notification
- Timeout-feature (free configurable)
- Multithreaded



FSM-Architecture

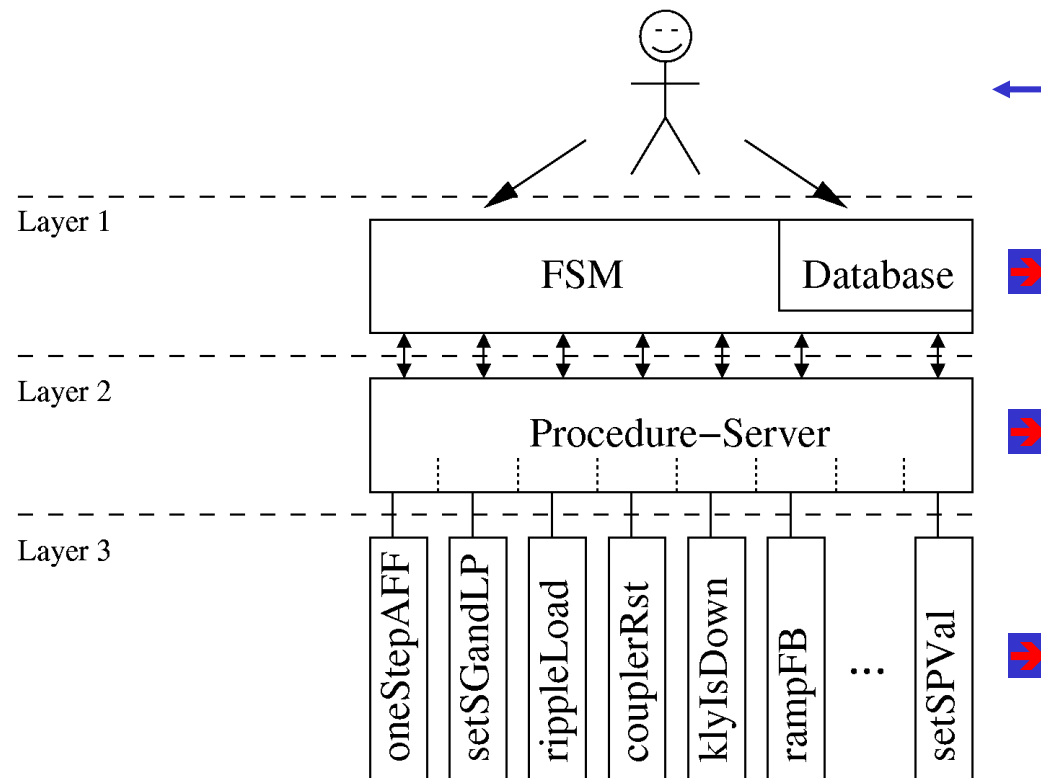


State-Machine

- **Moore-FSM:**
 - “Do something on enter”
 - Here: trigger a procedure
- **Flexible design**
 - On-line reconfigurable
 - Off-line “restructurable”
- **Current design: model the expert-operator**
- “Database” stores all settings, calibration-tables, parameters for the procedures, ...



FSM-Architecture



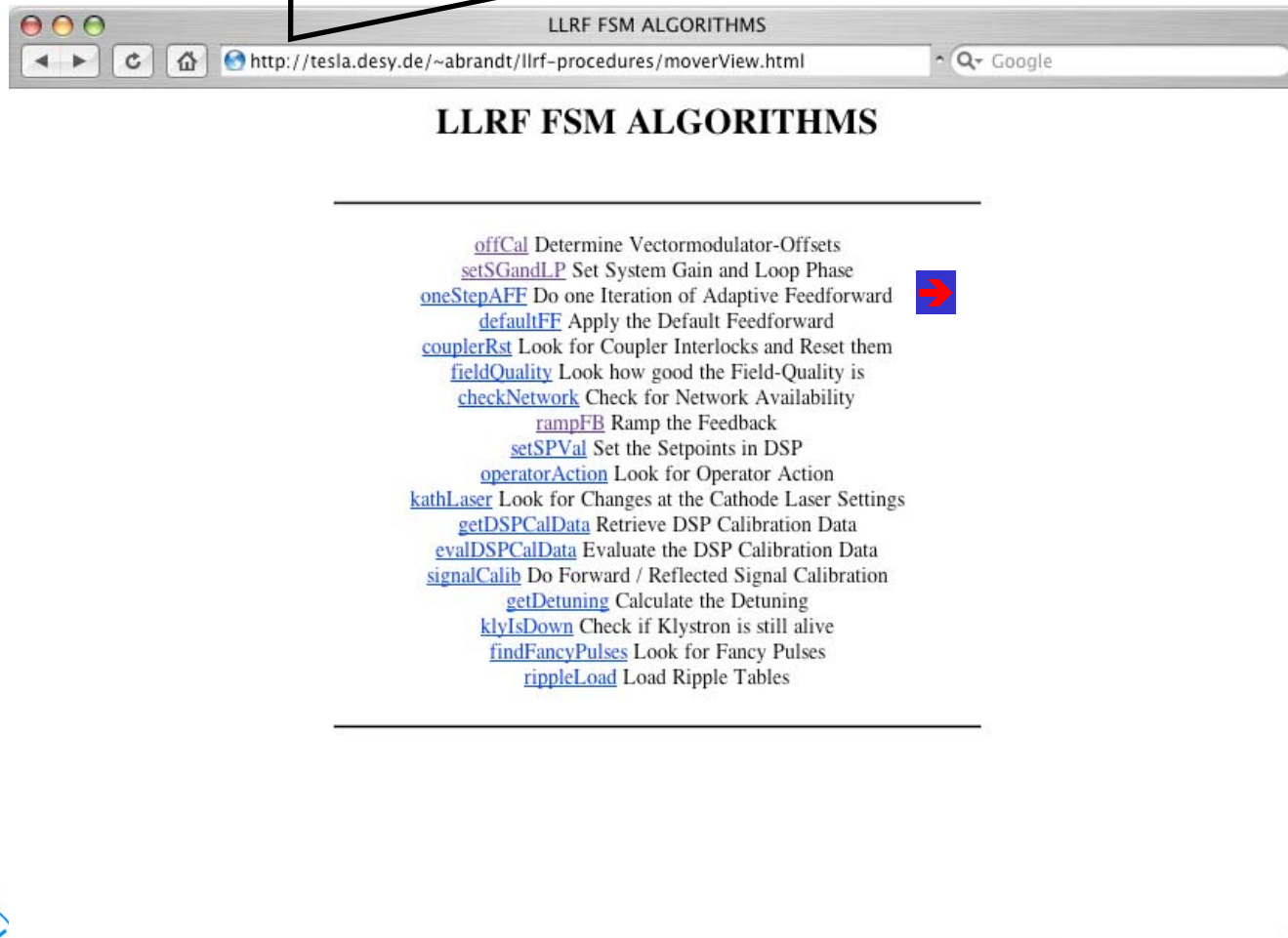
User-Interface

- Simple view for the operator →
- Extended view for the expert →



Procedure-Documentation

<http://tesla.desy.de/~abrandt/llrf-procedures/moverView.html>



low level radio frequency

FLASH Seminar May 29th 2006 6/32

“oneStepAFF” Web-Documentation

ONE ADAPTIVE FEEDFORWARD ITERATION

[NAME](#)
[DESCRIPTION](#)
[RETURN-VALUES](#)
[IMPACT](#)
[INSTALLED](#)
[QUESTIONS](#)

NAME

oneStepAFF – One iteration of adaptive feedforward

DESCRIPTION

Performs one step of the iteration for adaptive feedforward.

The algorithm only does something, if the checkbox in the FSM-control-panel is ticked...

The algorithm is iterative, so you can perform as many steps as you like, until the field quality is as you wish it to be. Usually, good convergence is already achieved after three iterations.

The algorithm requires the feedback to be on.

The algorithm does a lot of consistency/exception-handling checks. If something suspicious occurs, the algorithm simply does nothing during the current iteration.

In the expert panel, one can adjust from which setpoint value on the algorithm will be active. Nothing is done if the current setpoint is below that value.

Since the current DSP-code is not compatible with the adaptive feedforward concept in case beam compensation is turned on, the algorithm will turn off the beam compensation in case it was on.

RETURN-VALUES

0=Adaption successful! OR: Feedforward was off. No adaption is done. OR: Feedback was off. No adaption done. OR: Successfully set default feedforward in case the checkbox is un-ticked.

1=Not allowed to touch tables (checkbox...) 2=Gradient lower than threshold. Nothing done.

3=Switched off old beam compensation.

4=Veto from BIS. Nothing done.

-10=doocs t/w error

-11=Data inconsistency (bandwidth out of range, signal too noisy...)

-12=Adaptive feedforward algorithm itself returned an error message (very unlikely)

-21=Config-file not found

IMPACT

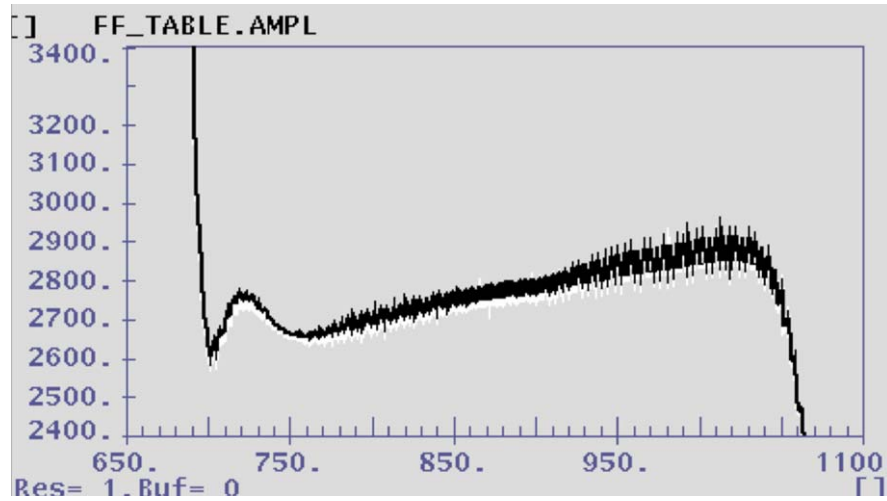


Adaptive Feedforward

QuickTime™ and a
Cinepak decompressor
are needed to see this picture.



Adaptive Feedforward

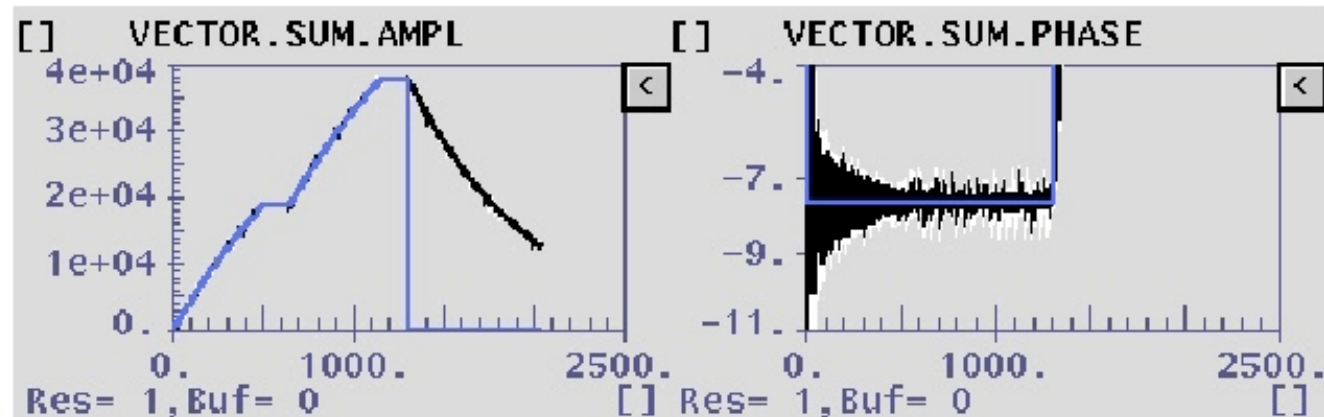


Adaptive FF w/ beam load
(ACC2/3, 30us, ~1nC)
Remember, this is just the FF contribution!

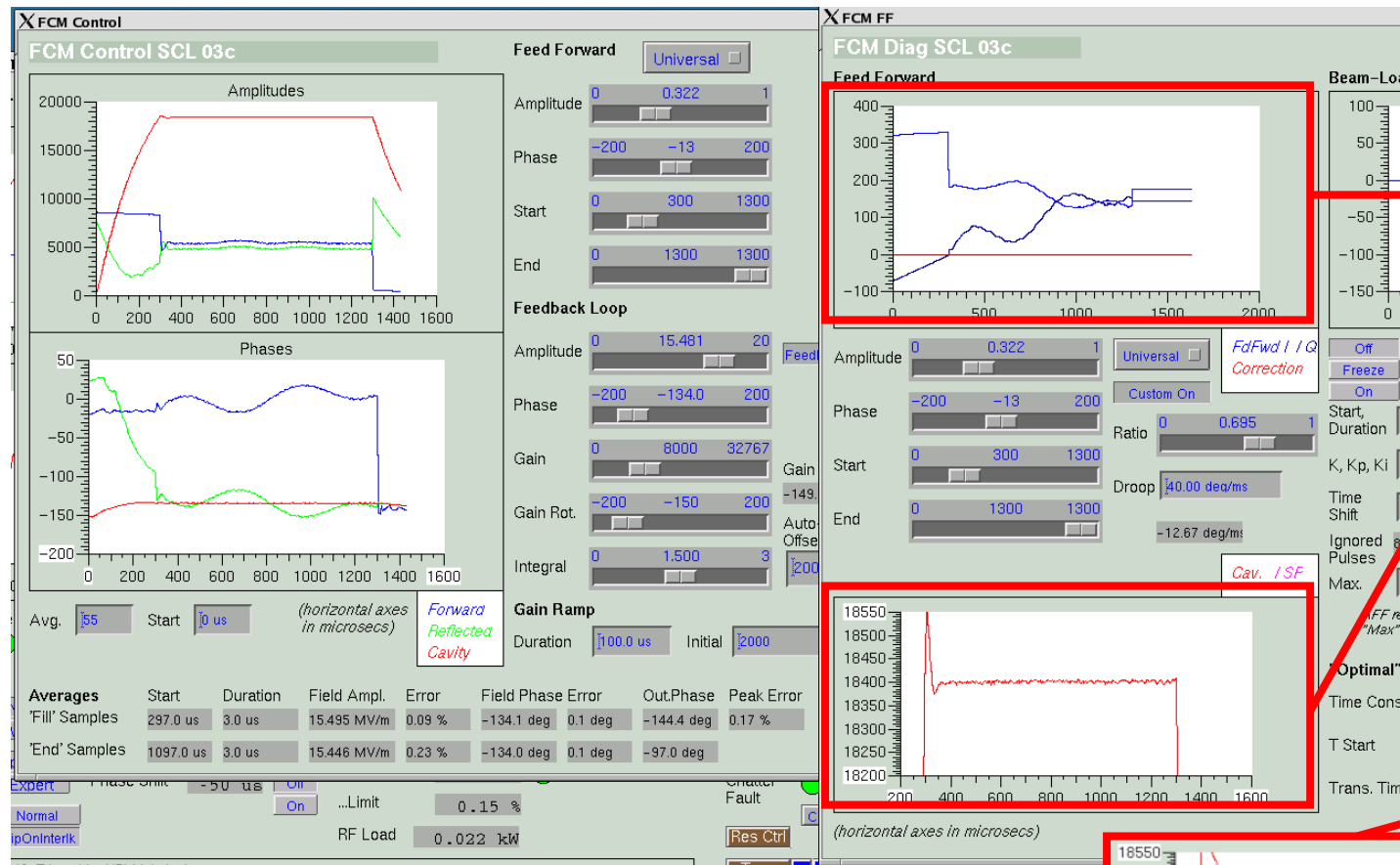
E-Log 10/3/2006, 14:15

Fancy pulses
w/ adaptive FF

E-Log 25/3/2006, 8:58



Adaptive Feedforward



Feedforward-Table

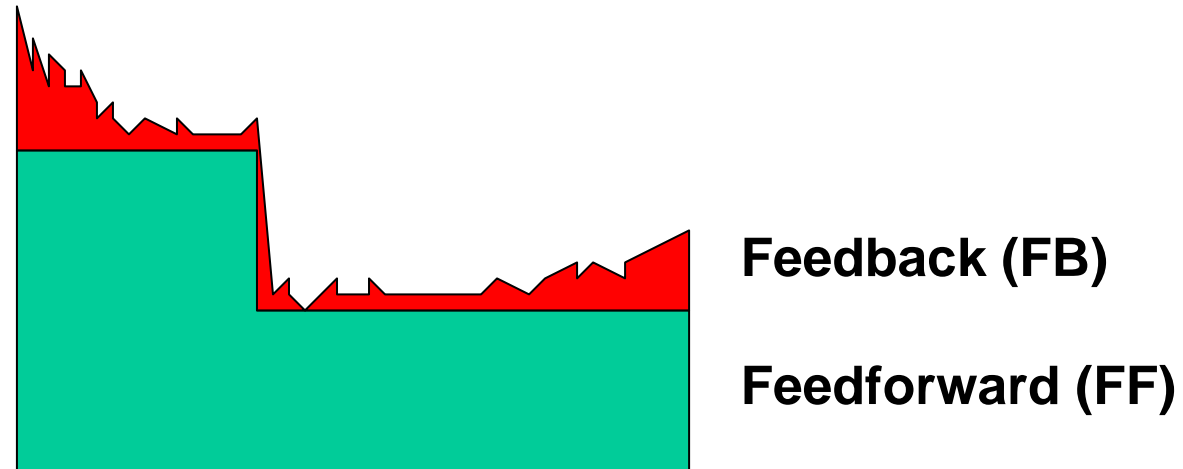
**Flatop w/
Adaptive FF
(3 Iterations)**

**Flatop w/o
Adaptive FF**

SNS LLRF Control Panel



Adaptive Feedforward



1st idea: $FF_{\text{new}} = FB_{\text{last}} + FF_{\text{last}}$...is instable :(

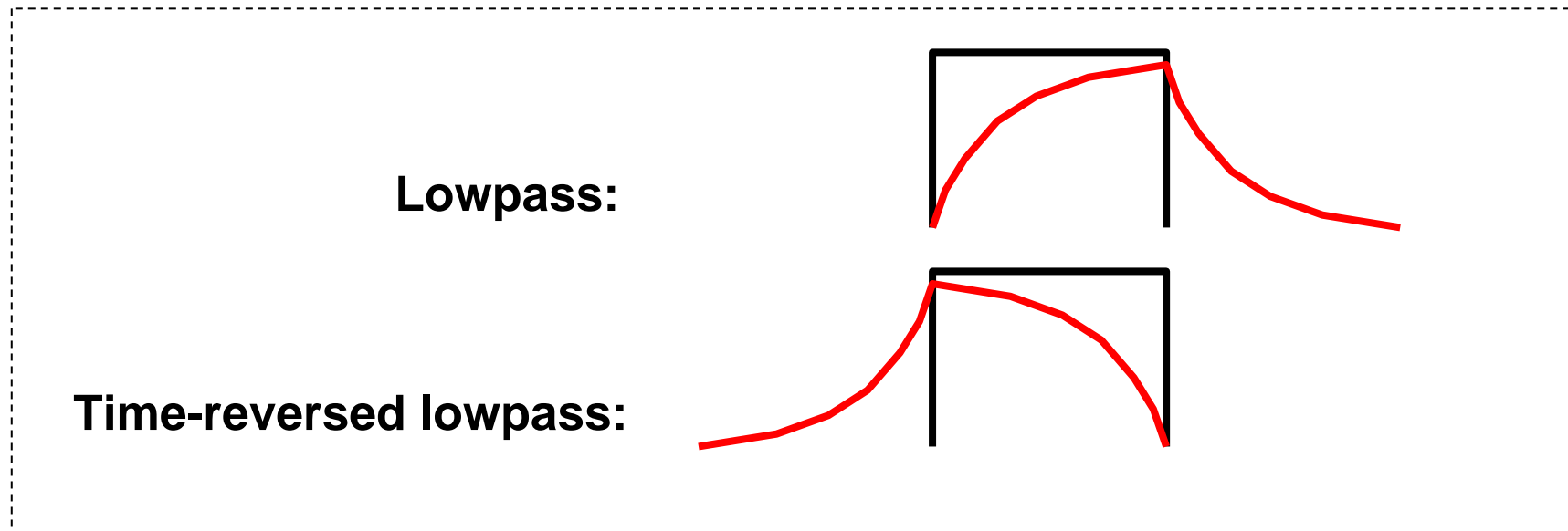
2nd idea: $FF_{\text{new}} = LP(FB_{\text{last}}) + FF_{\text{last}}$...is even worse :(

low-pass



Adaptive Feedforward

3rd idea: Instead of a low-pass use a “time-reversed low-pass”:



$$FF_{\text{new}} = \text{TRLP}(FB_{\text{last}}) + FF_{\text{last}} \quad \dots \text{is surprisingly stable :)}$$

time-reversed low-pass

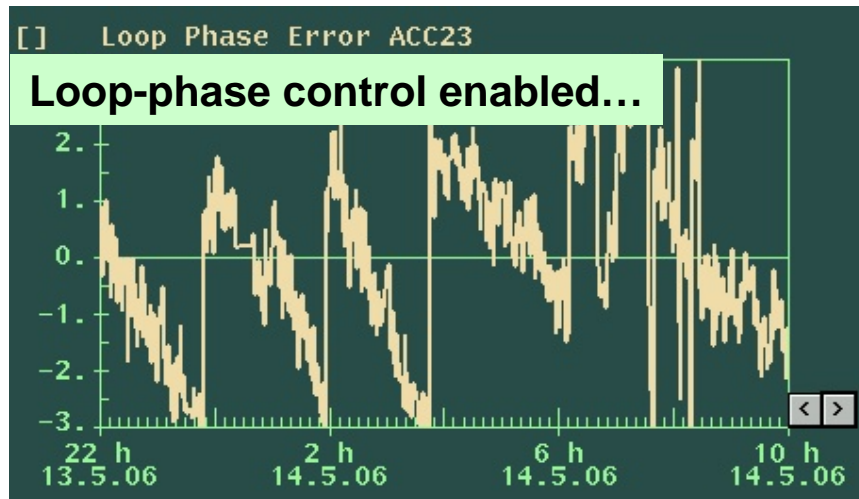


Adaptive Feedforward

- Currently used: time-reversed lowpass at **2.5kHz** (just 3 lines Matlab code!)
- Good results after **2-3 iterations**
- However: **exception handling** most important!



Loop Phase Correction



Loop Phase / System Gain Algorithm Configuration

Minimum system-gain:

▲▲▲▲ ▲▲
+ 0.07
▼▼▼▼ ▼▼

Maximum system-gain:

▲▲▲▲ ▲▲
+ 0.13
▼▼▼▼ ▼▼

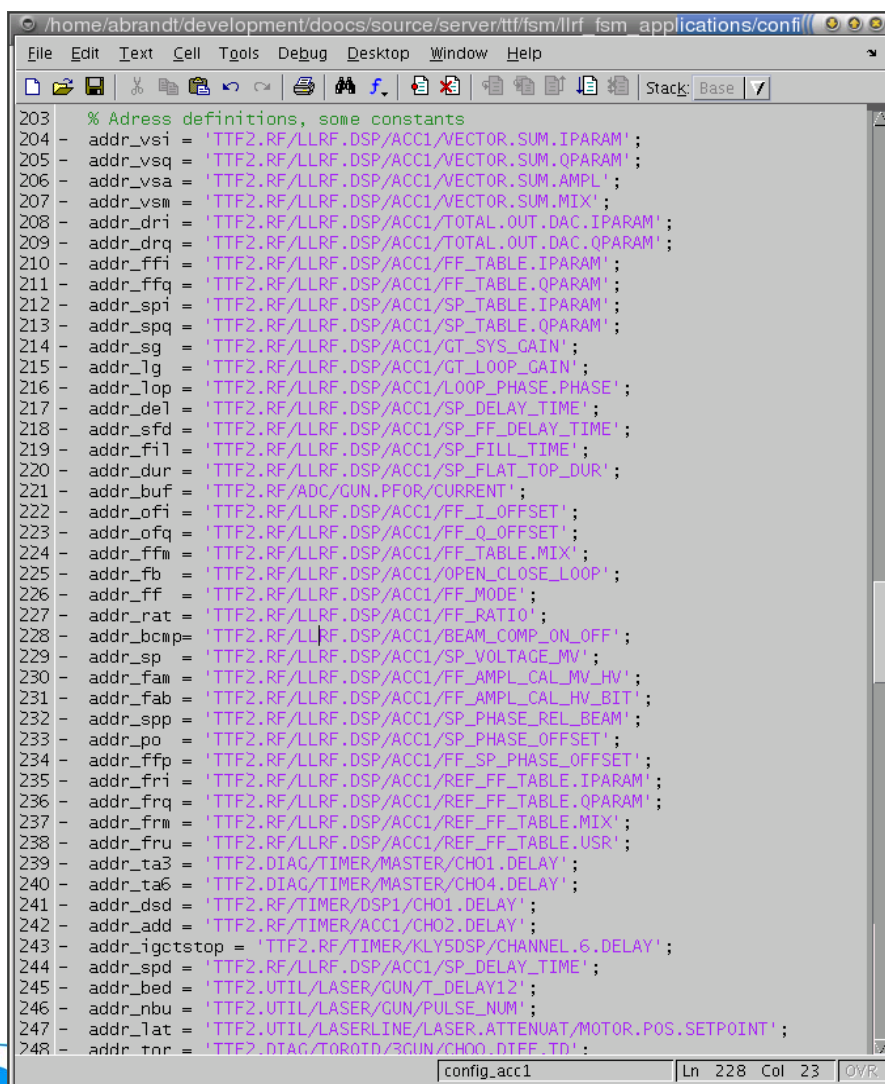
Algorithm active only for
SP higher than [MV/m]

▲▲▲▲ ▲▲
+ 35.00
▼▼▼▼ ▼▼

Enable for short pulses

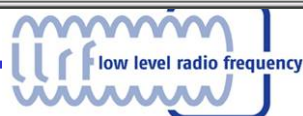


Config File



```
% Address definitions, some constants
203 - addr_vsi = 'TTF2.RF/LLRF.DSP/ACC1/VECTOR.SUM.IPARAM';
204 - addr_vsq = 'TTF2.RF/LLRF.DSP/ACC1/VECTOR.SUM.QPARAM';
205 - addr_vsa = 'TTF2.RF/LLRF.DSP/ACC1/VECTOR.SUM.AMPL';
206 - addr_vsm = 'TTF2.RF/LLRF.DSP/ACC1/VECTOR.SUM.MIX';
207 - addr_dri = 'TTF2.RF/LLRF.DSP/ACC1/TOTAL.OUT.DAC.IPARAM';
208 - addr_drq = 'TTF2.RF/LLRF.DSP/ACC1/TOTAL.OUT.DAC.QPARAM';
209 - addr_ffl = 'TTF2.RF/LLRF.DSP/ACC1/FF_TABLE.IPARAM';
210 - addr_ffq = 'TTF2.RF/LLRF.DSP/ACC1/FF_TABLE.QPARAM';
211 - addr_spi = 'TTF2.RF/LLRF.DSP/ACC1/SP_TABLE.IPARAM';
212 - addr_spq = 'TTF2.RF/LLRF.DSP/ACC1/SP_TABLE.QPARAM';
213 - addr_sg = 'TTF2.RF/LLRF.DSP/ACC1/GT_SYS_GAIN';
214 - addr_lg = 'TTF2.RF/LLRF.DSP/ACC1/GT_LOOP_GAIN';
215 - addr_lop = 'TTF2.RF/LLRF.DSP/ACC1/LOOP_PHASE.PHASE';
216 - addr_del = 'TTF2.RF/LLRF.DSP/ACC1/SP_DELAY_TIME';
217 - addr_sfd = 'TTF2.RF/LLRF.DSP/ACC1/SP_FF_DELAY_TIME';
218 - addr_fil = 'TTF2.RF/LLRF.DSP/ACC1/SP_FILL_TIME';
219 - addr_dur = 'TTF2.RF/LLRF.DSP/ACC1/SP_FLAT_TOP_DUR';
220 - addr_buf = 'TTF2.RF/ADC/GUN.PFOR/CURRENT';
221 - addr_ofi = 'TTF2.RF/LLRF.DSP/ACC1/FF_I_OFFSET';
222 - addr_ofq = 'TTF2.RF/LLRF.DSP/ACC1/FF_Q_OFFSET';
223 - addr_ffm = 'TTF2.RF/LLRF.DSP/ACC1/FF_TABLE.MIX';
224 - addr_fb = 'TTF2.RF/LLRF.DSP/ACC1/OPEN_CLOSE_LOOP';
225 - addr_ff = 'TTF2.RF/LLRF.DSP/ACC1/FF_MODE';
226 - addr_rat = 'TTF2.RF/LLRF.DSP/ACC1/FF_RATIO';
227 - addr_bcmp = 'TTF2.RF/LLRF.DSP/ACC1/BEAM_COMP_ON_OFF';
228 - addr_sp = 'TTF2.RF/LLRF.DSP/ACC1/SP_VOLTAGE_MV';
229 - addr_fam = 'TTF2.RF/LLRF.DSP/ACC1/FF_AMPL_CAL_MV_HV';
230 - addr_fab = 'TTF2.RF/LLRF.DSP/ACC1/FF_AMPL_CAL_HV_BIT';
231 - addr_spp = 'TTF2.RF/LLRF.DSP/ACC1/SP_PHASE_REL_BEAM';
232 - addr_po = 'TTF2.RF/LLRF.DSP/ACC1/SP_PHASE_OFFSET';
233 - addr_ffp = 'TTF2.RF/LLRF.DSP/ACC1/FF_SP_PHASE_OFFSET';
234 - addr_fri = 'TTF2.RF/LLRF.DSP/ACC1/REF_FF_TABLE.IPARAM';
235 - addr_frq = 'TTF2.RF/LLRF.DSP/ACC1/REF_FF_TABLE.QPARAM';
236 - addr_frm = 'TTF2.RF/LLRF.DSP/ACC1/REF_FF_TABLE.MIX';
237 - addr_fru = 'TTF2.RF/LLRF.DSP/ACC1/REF_FF_TABLE.USR';
238 - addr_ta3 = 'TTF2.DIAG/TIMER/MASTER/CHO1.DELAY';
239 - addr_ta6 = 'TTF2.DIAG/TIMER/MASTER/CHO4.DELAY';
240 - addr_dsd = 'TTF2.RF/TIMER/DSP1/CHO1.DELAY';
241 - addr_add = 'TTF2.RF/TIMER/ACC1/CHO2.DELAY';
242 - addr_igctstop = 'TTF2.RF/TIMER/KLY5DSP/CHANNEL.6.DELAY';
243 - addr_spd = 'TTF2.RF/LLRF.DSP/ACC1/SP_DELAY_TIME';
244 - addr_bed = 'TTF2.UTIL/LASER/GUN/T_DELAY12';
245 - addr_nbu = 'TTF2.UTIL/LASER/GUN/PULSE_NUM';
246 - addr_lat = 'TTF2.UTIL/LASERLINE/LASER.ATTENUAT/MOTOR.POS.SETPOINT';
247 - addr_tor = 'TTF2.DIAG/TOROTD/3GUN/CHO0.DIFF_TD';
```

...all RF-stations have identical algorithms with individual config-files.

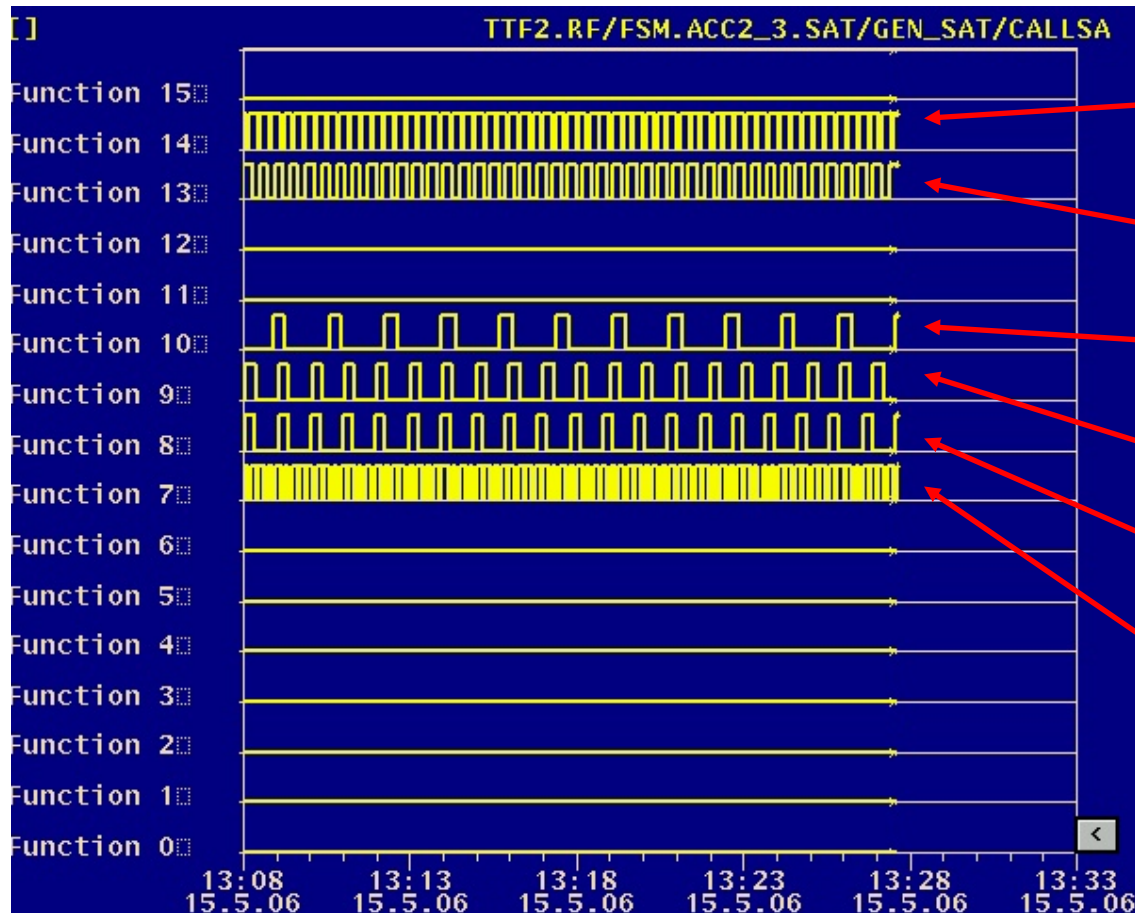


Procedure Server

Configuration		Timeout	Short Description	Human-Readable Result	Numerical Res.		
Hist 0-15							
Hist 16-31							
FUN0	11rf/runDummy_csh out0.dat 11rf/out0.dat	1500		Operation Successful!	0	1.96	0.28
FUN1	11rf/runDocsSolap12obj/Server/tkf/Kluc 11rf/out1.dat	1500		Script execution error.	-99	0	0
FUN2	11rf/runOFFKcal_csh out2.dat 11rf/out2.dat	1500	Correcting Offsets.	Script execution error.	-99	0	0
FUN3	11rf/runSetScandLP.sh out3.dat 11rf/out3.dat	1500	Correcting loopphase.	Corrected loop phase.	2	-3.84	0.12
FUN4	11rf/runOneStepAFMSP_csh out4.dat 11rf/out4.dat	1500	Adapting Feedforward (DSP-par.).	Applied zero Feedforward (Feedforward was off)	0	0	0
FUN5	11rf/runOneStepAF.sh out5.dat 11rf/out5.dat	1500	Adapting Feedforward	Feedback is off. No FF-adaption possible.	0	0	0
FUN6	11rf/runDefaultFF_csh out6.dat 11rf/out6.dat	1500	Applying default Feedforward.	Successfully set default feedforward.	0	0	0
FUN7	11rf/runCouplerSet7.sh out7.dat 1 11rf/out7.dat	1500	Checking coupler interlocks.	Executing...	-98	0	0
FUN8	11rf/runSetScandLP.sh out8.dat 1 11rf/out8.dat	1500	Checking loopphase.	No drive from 11rf is applied.	0	0	0
FUN9	11rf/runFieldQuality.sh out9.dat 11rf/out9.dat	1500	Checking data quality.	FB=0 or FF=0! Data quality is unacceptable.	9	inf	117.42
FUN10	11rf/runCheckNetwork7.sh out10.dat 11rf/out10.dat	1500	Checking network.	Network works fine.	0	0	0
FUN11	11rf/runRampFB_csh out11.dat 11rf/out11.dat	1500	Ramping Feedback.	Successfully ramped FB to target value!	0	0	0
FUN12	11rf/runSetSPW1_csh out12.dat 11rf/out12.dat	1500	Setting amplitude and phase.	Successfully ramped SP to target value!	0	0	0
FUN13	11rf/runOperatorAction.sh out13.dat 11rf/out13.dat	1500	Looking for operator action.	Executing...	-98	0	0
FUN14	11rf/runKathLaser.sh out14.dat 11rf/out14.dat	1500	Checking cathode laser settings.	Executing...	-98	0	0
FUN15	11rf/runGetDSPCalData_csh out15.dat 11rf/out15.dat	1500	Retrieving DSP calibration-data.	Script execution error.	-99	0	0
FUN16	11rf/runEvalDSPCalData_csh out16.dat 11rf/out16.dat	1500	Evaluating DSP-Cal-Data.	Script execution error.	-99	0	0
FUN17	11rf/runSignalCal167.sh out17.dat 11rf/out17.dat	1500	Calculating cavity signal calibration.	There is no drive at all!	2	0	0
FUN18	11rf/runGetDetunings_csh out18.dat 11rf/out18.dat	1500	Calculating detunings.	Calculating detuning done.	0	0	0
FUN19	11rf/runSetSPW1_csh out19.dat 11rf/out19.dat	1500	Setting amplitude and phase (slowly).		0	0	0
FUN20	11rf/runKlyIsAlive.sh out20.dat 11rf/out20.dat	1500	Looking if Klystron is alive.	Executing...	-98	0	0
FUN21	11rf/runFindFancyPulses.sh out21.dat 11rf/out21.dat	1500	Looking for fancy pulses.	Feedforward is off.	0	0	0
FUN22	offCal AC436 out22.dat out22.dat	0		Script execution error.	-99	0	0
FUN23	setScandLP AC436 out23.dat out23.dat	0		Calculated bandwidth out of range. (Maybe there is no drive signal at 411K)	411K	0	0
FUN24	11rf/runRippleLoad.sh out24.dat 11rf/out24.dat	500	Applying ripple-correction.	Script execution error.	-99	0	0
FUN25	11rf/runRippleLoad.sh out25.dat 0 11rf/out25.dat	500	Restoring zero ripple-table.	Script execution error.	-99	0	0
FUN26	defaultFF AC436 out26.dat out26.dat	0		Script execution error.	-99	0	0
FUN27		0			0	0	0
FUN28	./runFsmKly4 out28.txt out28.txt	0		Script execution error.	-99	0	0
FUN29	./runFsmKly5 out29.txt out29.txt	0		Script execution error.	-99	0	0



Procedure History



Check Cathode Laser

Check Operator Action

Check config file (network availability)

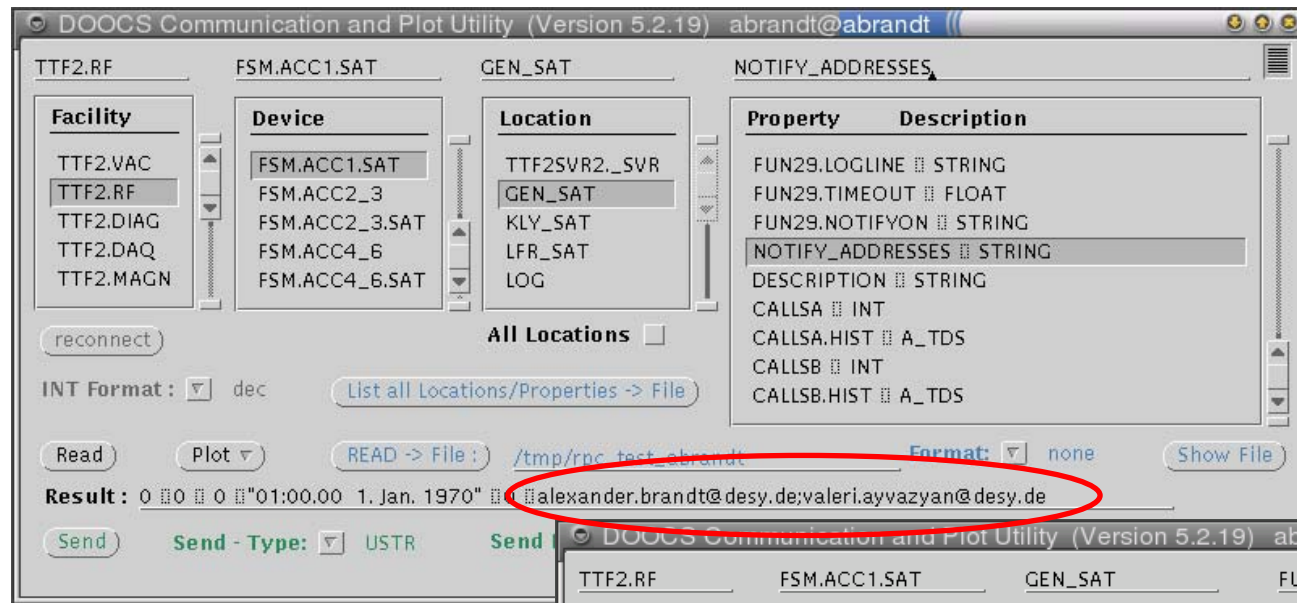
Monitor data quality

Check for loop phase

Check for coupler interlocks



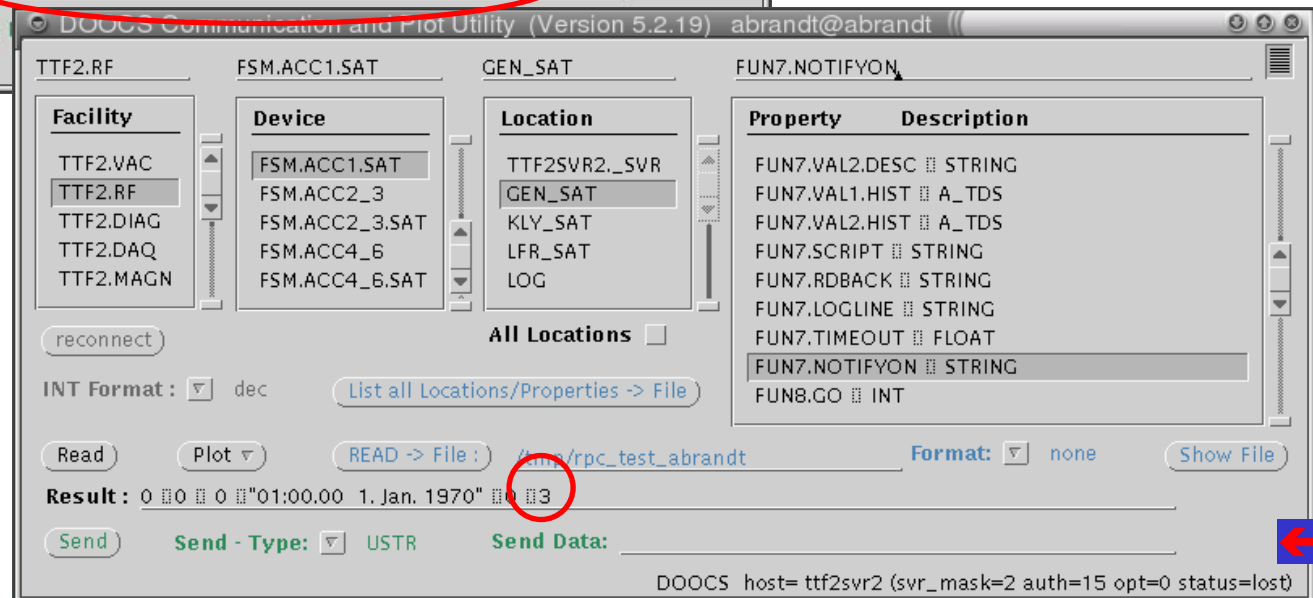
Email-Notification



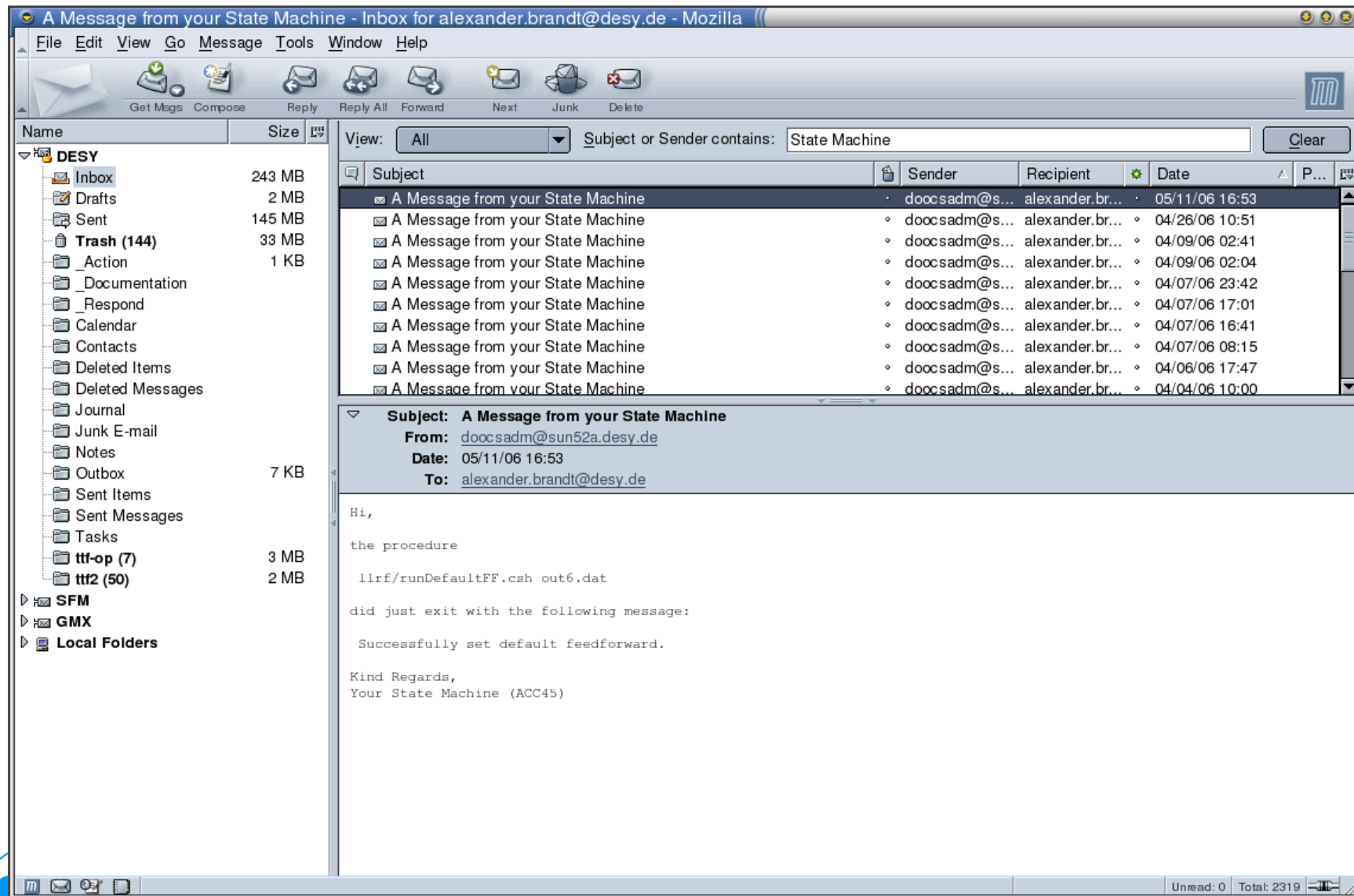
Email-addresses for this RF-station...

Example: ➡

Notify-Condition for procedure in slot 7



Email-Example



On-Line Reconfigurability

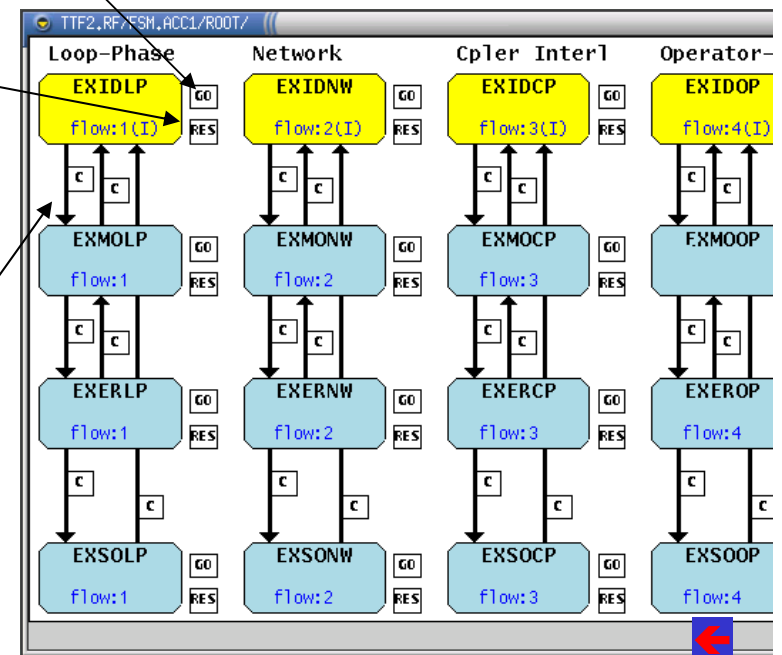
A click here defines what happens on enter...

- can be a number (like 'wait 25 pulses'),
- can be an event (make transition somewhere),
- can be a procedure
- can be a combination of them.

Where to find the numerical result once the procedure (timer) has finished - can be any DOOCS-address!

Conditions, that the result is compared to (which lead to a transition)

- can be (a list of) number(s)
- can be a 'not', 'else', 'all'



Off-Line Restructurability

```

emacs@
File Edit Options Buffers Tools C++ Help

//// DO NOT EDIT THIS AND NEXT TWO ROWS
// init function for state 'EXERDQ'
int ROOT_EXERDQ_init_action(FSMstate *st_p_)
{

    fputs("ROOT_EXERDQ:: \"init\" event procedure: ROOT_EXERDQ_init_action \n", stderr);

    TStateLogic* sd=TStateLogic::factory("EXERDQ");
    sd->set_go("ROOT_EXCEPTION.EXERDQ_GO");
    sd->set_res("ROOT_EXCEPTION.EXERDQ_RES");
    sd->add_event("EXERDQ", "exerdq_exmodq", "ROOT_EXCEPTION.EXERDQ_T1");
    sd->add_event("EXERDQ", "exerdq_eksodq", "ROOT_EXCEPTION.EXERDQ_T2");

    return ST_OK;
}

//// DO NOT EDIT THIS AND NEXT TWO ROWS
// enter function for state 'EXERDQ'
int ROOT_EXERDQ_enter_action(FSMstate *st_p_)
{

    fputs("ROOT_EXERDQ:: \"enter\" event procedure: ROOT_EXERDQ_enter_action \n", stderr);

    TStateLogic* sd=TStateLogic::factory("EXERDQ");
    sd->enter(st_p_);

    return ST_OK;
}

//// DO NOT EDIT THIS AND NEXT TWO ROWS
// during function for state 'EXERDQ'
int ROOT_EXERDQ_during_action(FSMstate *st_p_)
{

    fputs("ROOT_EXERDQ:: \"during\" event procedure: ROOT_EXERDQ_during_action \n", stderr);

    TStateLogic* sd=TStateLogic::factory("EXERDQ");
    sd->during(st_p_);

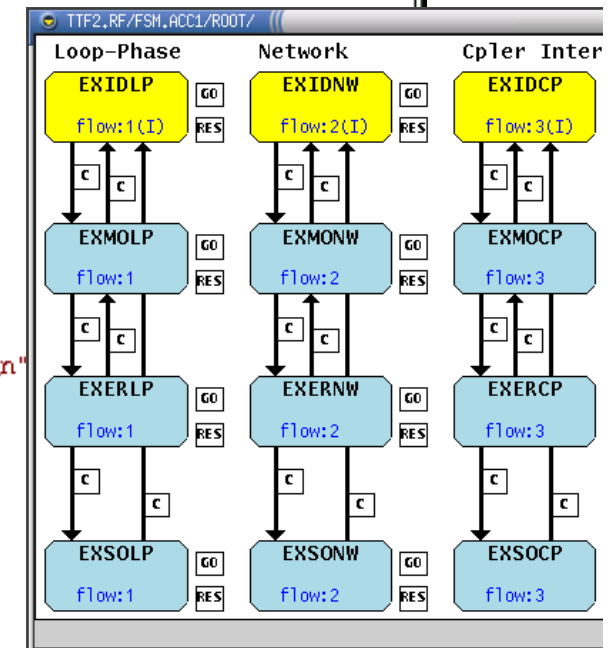
    return ST_OK;
}

```

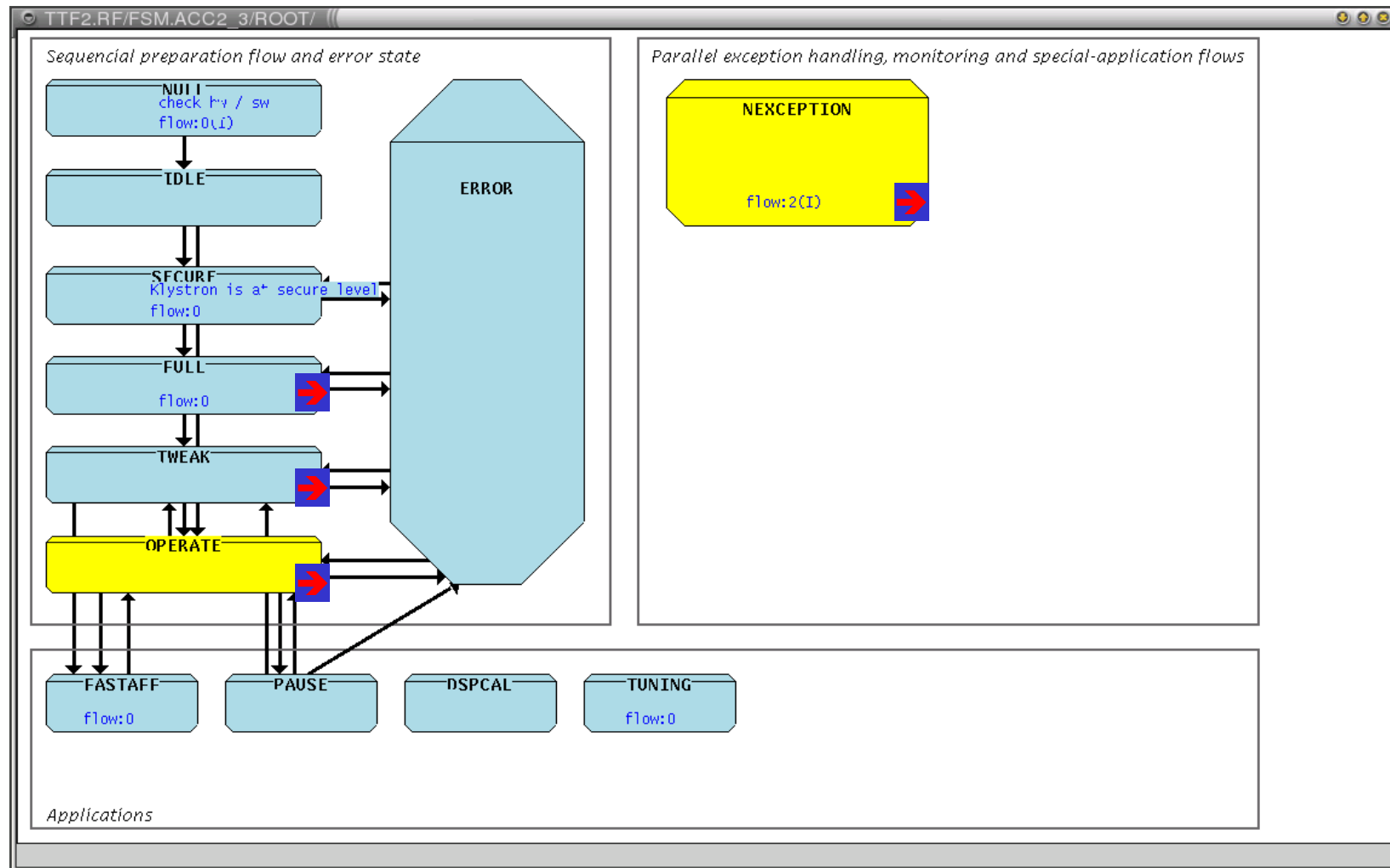
init

enter

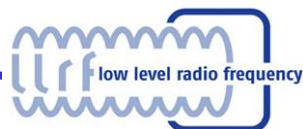
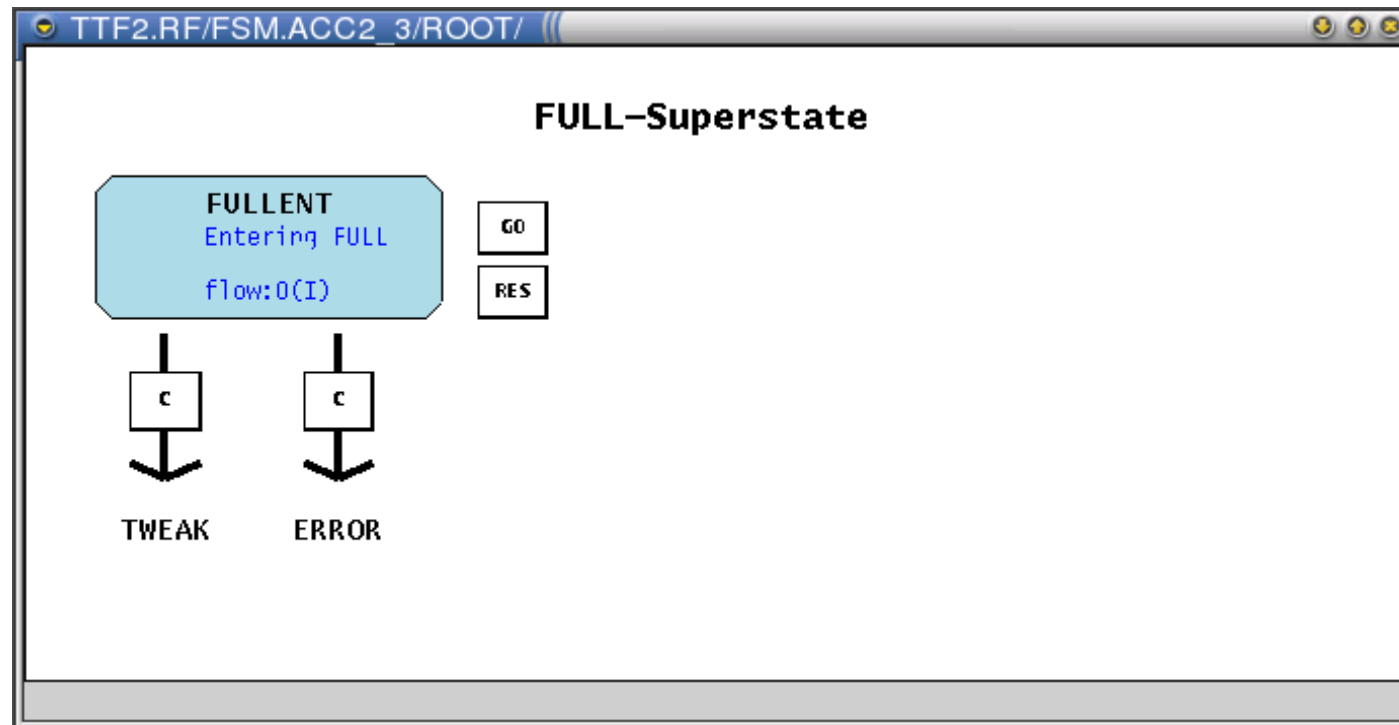
during



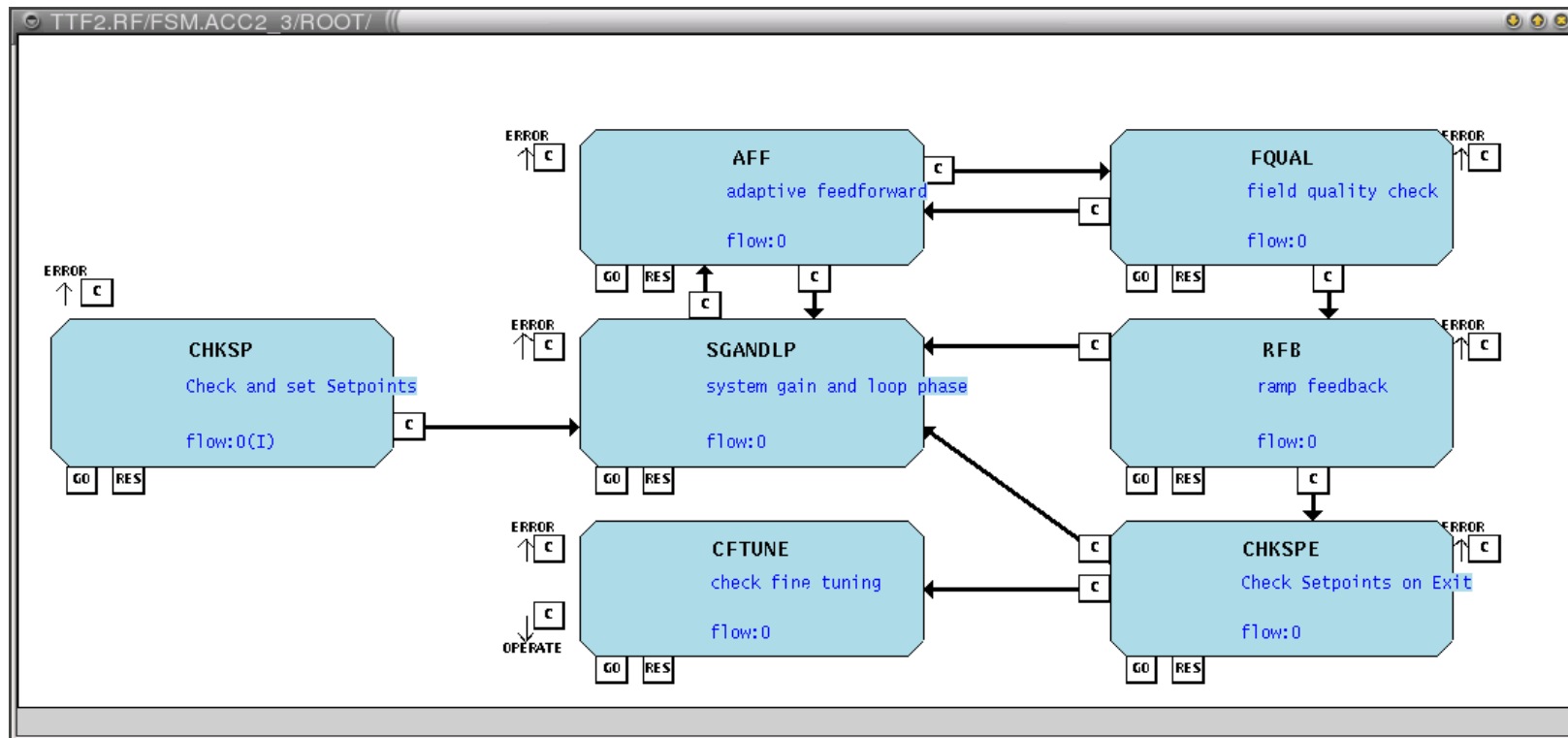
FSM Top Level View



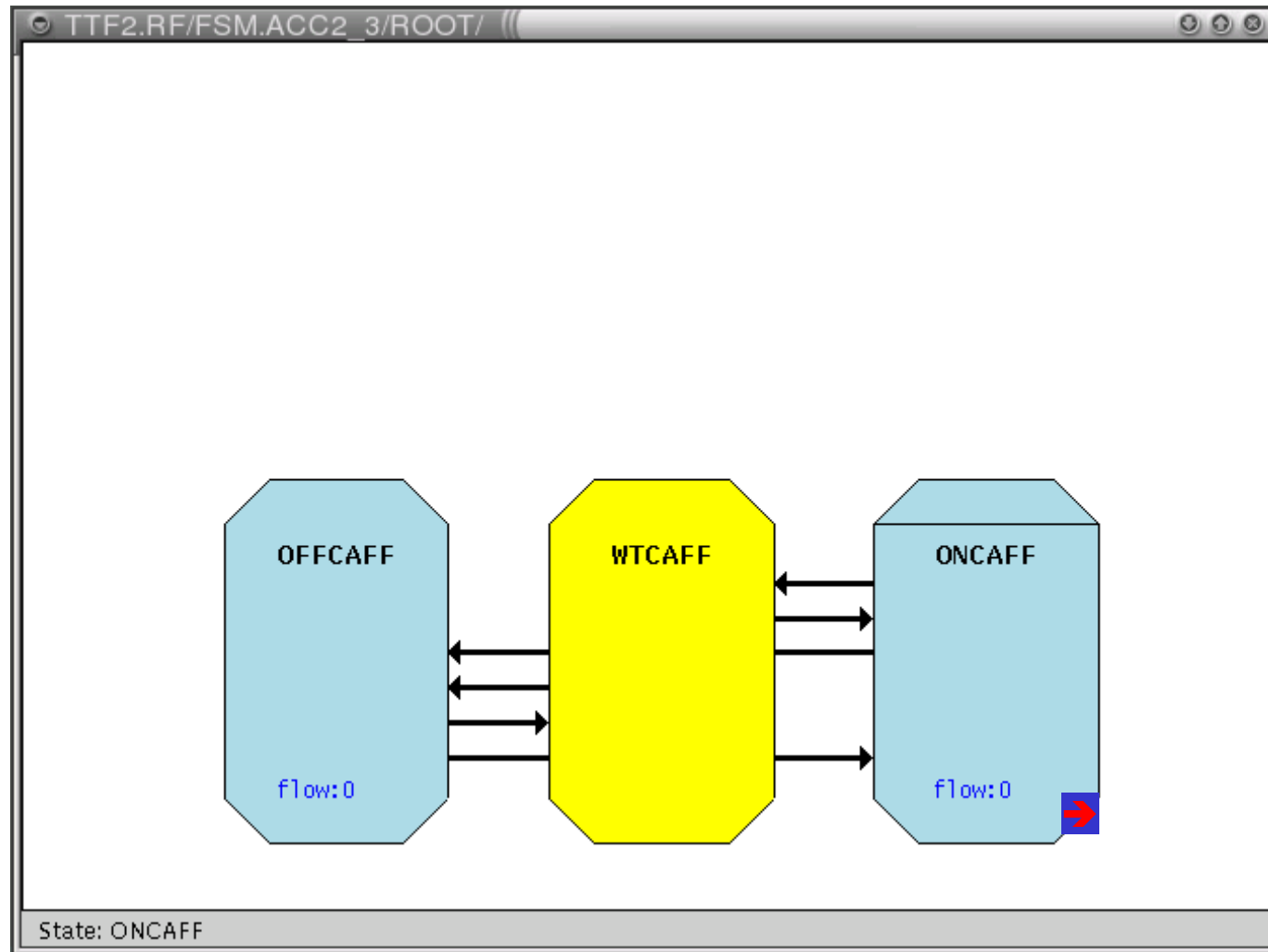
FSM Full State



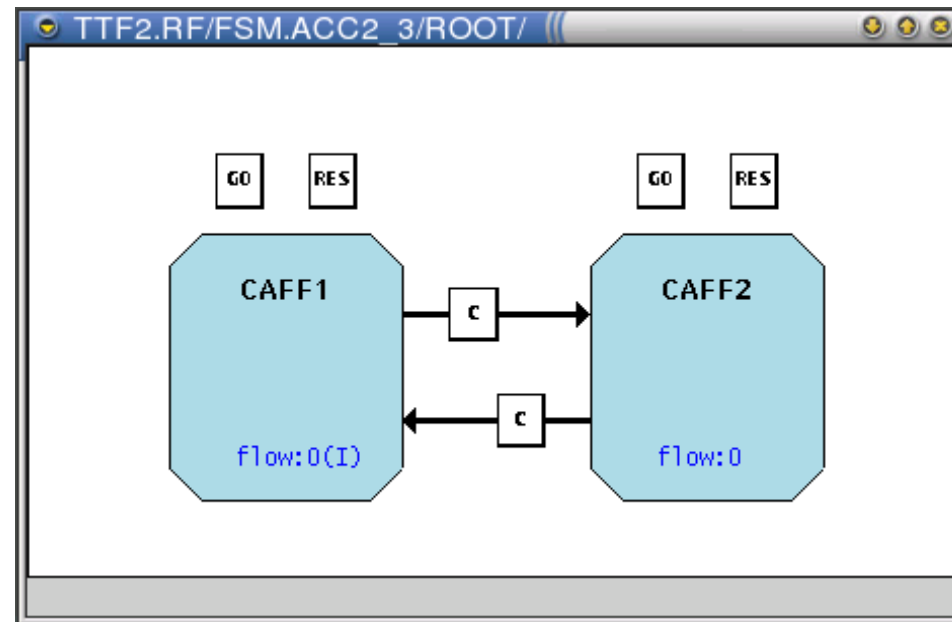
FSM Tweak State



FSM Operate State



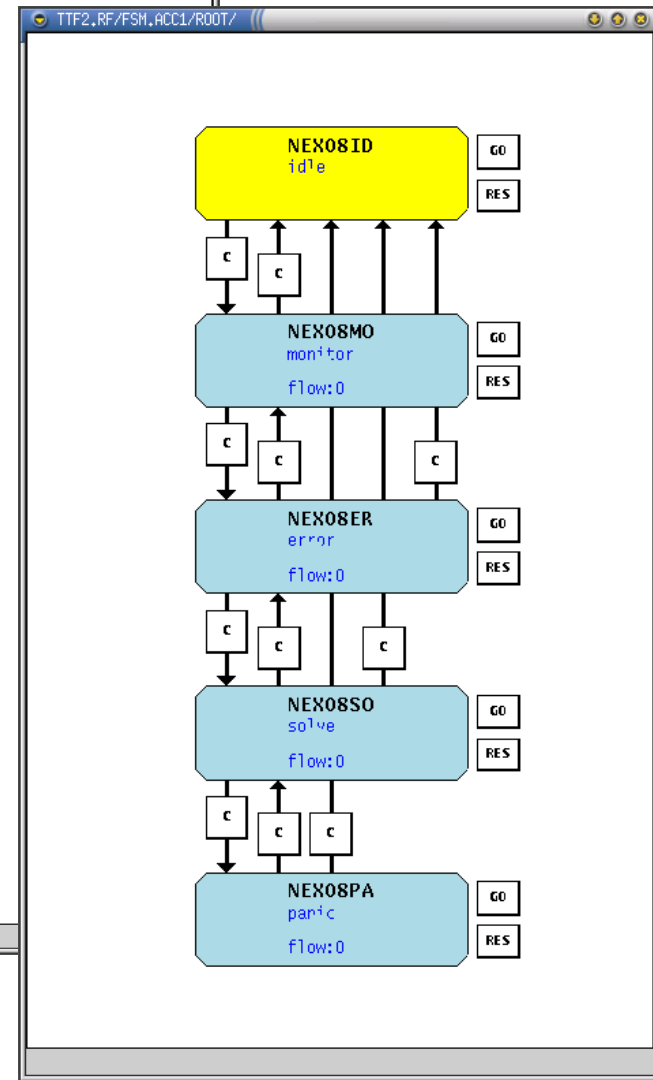
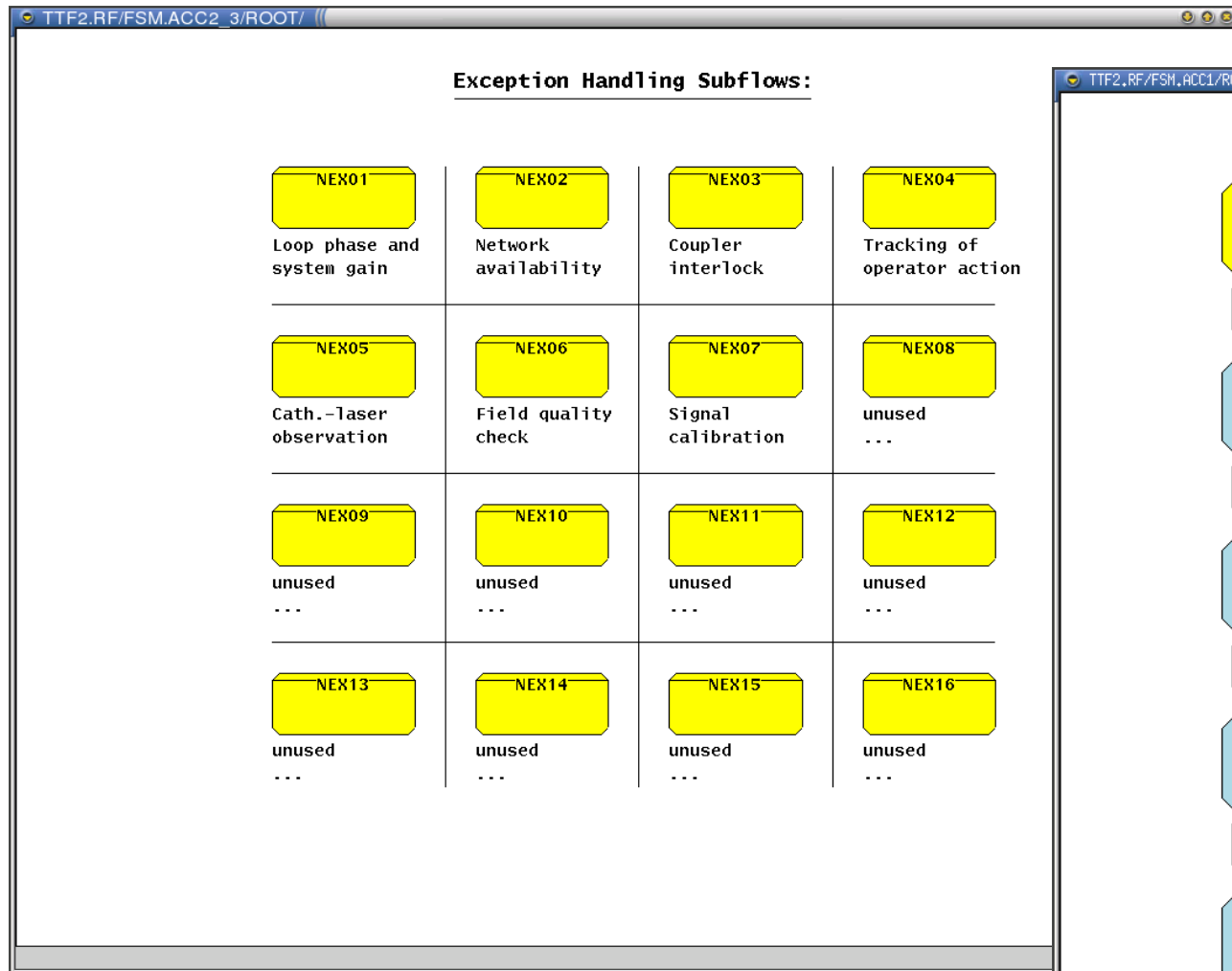
FSM ONCAFF State



low level radio frequency



FSM Exception State

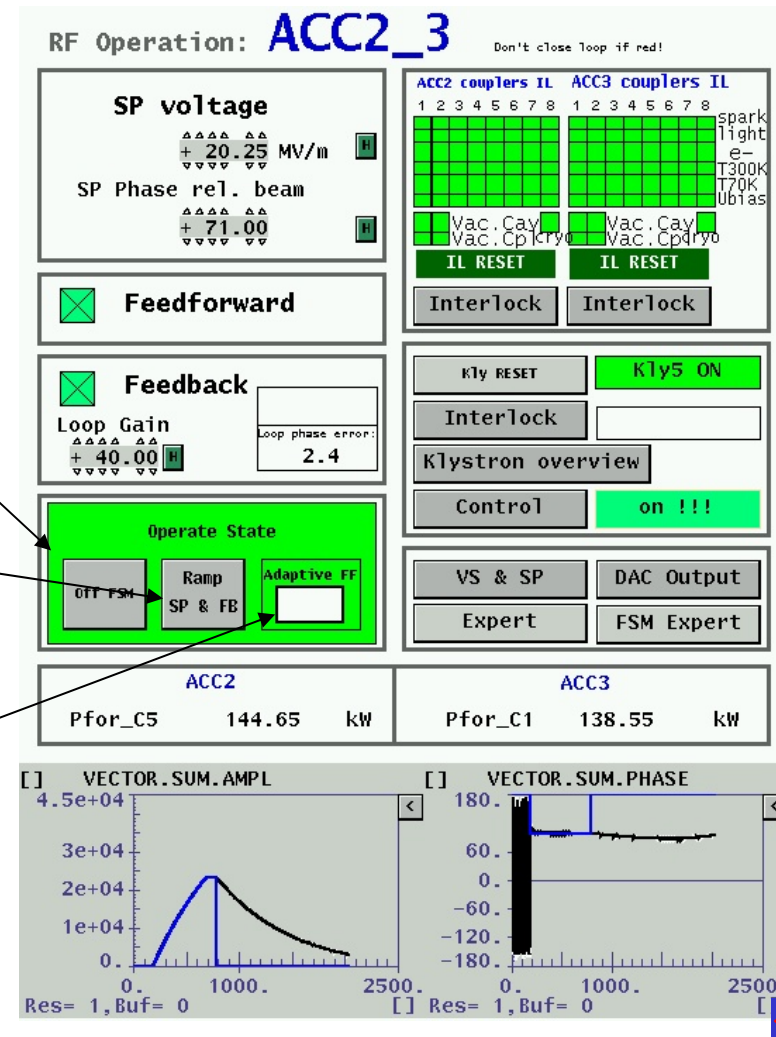


Simple Operators View

Switch off FSM

Ramp RF to the target values
(...)

Enable adaptive FF



FSM-Expert View

Checkboxes determine the behavior of the algorithms (and the algorithms determine the behavior of the FSM).

Scrolling messages from all procedures

Debug level

Target values are automatically updated while operator is working with the DSP!

...but only as long as this is desired!

Algorithm expert settings

Messages:

ALL INFO WARN ERR

17:02:18 Data quality is high. :) [9:0]
17:02:14 Klystron is ready! [20:0]
17:02:12 Checking coupler interlocks.
17:02:11 Looking for operator action.
17:02:09 Checking cathode laser settings.
17:02:06 No interlock observed. [7:0]
17:02:05 Cathode laser unchanged. [14:0]
17:02:05 Loop Phase and System Gain look fine. [8:0]
17:02:00 Checking data quality.
17:01:58 Looking if Klystron is alive.
17:01:58 No operator action detected. [13:0]

Simple operators view

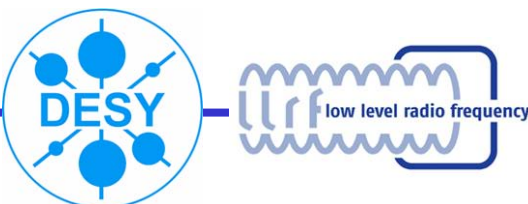
Operate State

off FSM Ramp SP & FB Adaptive FF

ROOT

LP-Expert AFF-Expert

Access to FSM-structure (for on-line reconfig)



Operation Experience

- “Permanent features”
 - **Loop phase** running with <1 error/week (fixed usually the next day)
 - **Adaptive feedforward** (rarely used) with ~ 1 error/week (fixed next day)
 - Few things run without operator awareness (**signal calibration, operator-tracking**)
- “Occasional features”
 - **DSP ramp up** after down: tested but not used
 - **DSP ramp down** after klystron trip: tested but not used
- “Optional Features”
 - **DSP calibration, detuning display**, ... just used by me from time to time



DDD FSM Framework

- Nice, but probably too inflexible
- That's why my implementation extended it by
 - **Procedure server** (with features like timeout and email notification)
 - **Factory-classes** for a simple reconfiguration (still needs compilation)
 - **Parser** that interprets online configuration (“go”, “res” and “c” - buttons)
- Re-working the automation should be as easy as re-designing a panel
- Extension of the DDD FSM Framework is in progress...



Finally...

- **FSM is in permanent commissioning - Valeri and I are activating features and testing them**
- **Adaptive Feedforward is**
 - available at FLASH
 - tested at SNS (to be implemented in August)
 - on it's way into the FPGA
- **Still: there is a lack of operator acceptance / cooperation**
- **Good experience made with the flexibility of this approach (fast bug-fixing, adaptation to operator needs)**



...

